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Using Swarm Intelligence in Cryptanalysis of Nonlinear Stream Cipher Cryptosystem

A THESIS

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My Beloved Father ... Mother,

Dear Husband,

and

My Children

With Love and Appreciation

Fatin

Abstract

The Swarm intelligence is a real an innovative computational way for solving some kinds of hard problems. This way is simulated by the behavior of social animals and insects such as bird flocks, fish schools, colonies of ants and hony bees etc.

The Particle swarm optimization (PSO) mimics the behavior of a swarm of bird flocks and school of fish. The Swarm behavior is modeled by number of particles in multidimensional space that have two parts: a position and a velocity.

Stream ciphers considered an important class of encryption algorithms. The Shift register sequences can be used in both cryptography and coding theory. There is a big wealth of theory about stream ciphers based on shift registers, which have been the workhorse of military cryptography since the beginnings of electronics.

This thesis aims to implement cryptanalysis system on stream cipher cryptosystems called PSO Cryptsnslysis System (PSOCS) using probable word plaintext attack, choosing three study cases, single Linear Feedback Shift Register (LFSR), which considered as a basic unit of stream cipher systems, and Linear cryptosystem and Threshold generator (as nonlinear cryptosystem) in the performance of PSO by find the actual solution of the System of Linear Equations (SLE) for any number of variables of the output of LFSR.

The application of the proposed PSOSC divided into two stages, first, constructing SLE's for the combined LFSR's in the genrator, and the second, is attacking the variables of SLE's which they are also the initial key values the of LFSR's. This thesis shows the good performance of PSOCS in finding the actual key of the three study cases.

The results of this research are implemented in Delphi version 10.0 visual programming languages exploiting the object oriented tools of this language.

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List of Symbols

Symbol	Description
B _i ,	the observed number of blocks
ei	simple events number i.
e _k	encryption key
Ei	Expected value of occurrence of outcome i
d _k	decryption key
f	Function <i>f</i>
F _n	finite field with n elements
G_i	The observed number of gaps
gcd(a,b)	greatest common divisor of a and b
lcm(a,b)	least common multiple of a and b
р	Prime number
S _i	the sequence i
n-KG	Key Generator consists of n LFSR's
\oplus	Exclusive-OR (XOR)
Si	The element i of the sequence S
S _r	Sequence generates from LFSR r
SL	the sequences generates from the linear systems
S _B	the sequences generates from the Brüer systems
S _P	the sequences generates from the product systems
$\langle G, * \rangle$	mathematical system consists of set G and operation *
≢	Not Congruent

List of Abbreviations

Abbreviatio	Meaning		
AES	Advanced Encryption Standard		
BDT	Binary Derivative Test		
С	Complex number		
С	Ciphertext space		
CE	Complementary Event		
CF	Combining Function		
CI	Correlation Immunity		
D	Decryption process (algorithm)		
DES	Data Encryption Standard		
E	Encryption process (algorithm)		
eSTREAM	ECRYPT Stream Cipher Project.		
FSE	Fast Software Encryption Conference		
GF	Galois field		
KG	Key Generator		
L	Length of Sequence		
LC	Linear Complexity		
LFSR	Linear Feedback Shift Register		
M	Message space		
MBSRT	Main Binary Standard Randomness Tests		
MLFSR	Maximal Linear Feedback Shift Register		
N	Natural number		
NLFSR	Nonlinear Feedback Shift Register		
R	Real Number		
RNG	Random Number Generator		
S	Sequence		
w.r.t.	with respect to		
Ζ	Integer number		

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Chapter One Basic Mathematical concepts 1.1 Introduction

The growth of the Internet has made government intelligence and police agencies nervous. They say that widely available encryption software could make wiretapping more difficult; their common reaction is to try to restrict the strength of encryption algorithms or require that spare copies of the keys are available somewhere for them to seize.

Cryptography is the study of mathematical techniques which are related to the aspects of information security such as confidentiality, data integrity, entity authentication, and data origin authentication [1].

This chapter introduces the basic concepts in different fields in mathematics, which the cryptography and cryptanalysis are needed, specially, in stream cipher systems.

1.2 Number Theory

Number theory, in mathematics, is primarily the theory of the properties of integers (whole numbers) such as parity, **divisibility**, **primarily**, **additively**, and **multiplicatively**, etc. In the next subsections we will investigate more detailed discussions about numbers.

1.2.1 *Primarily* [2]

Definition (1.1): A positive integer n>1 that has only two distinct factors, 1 and n itself (when these are different), is called **prime**; otherwise, it is called **composite**. The first few prime numbers are: 2,3,5,7,11,13,17,....

<u>Remark (1.1)</u>:

- It is interesting to note that primes thin out: there are eight up through 20, but only three between 80 and 100.
- 2. Note that 2 is the only even prime, all the rest are odd.

1.2.2 Multiplicatively

Theorem (1.1): [3] (the fundamental theorem of arithmetic)

Any positive integer n>1 can be written uniquely in the following prime factorization form:

$$n = p_1^{\alpha_1} p_2^{\alpha_2} \cdots p_k^{\alpha_k} = \prod_{i=1}^k p_i^{\alpha_i} \qquad \dots (1.1)$$

where $p_1 < p_2 < ... < p_k$ are primes, and $\alpha_1, \alpha_2, ..., \alpha_k$ are positive integers.

Example (1.1) [4]: The following are prime factorization of n for n=1999, 2000, ..., 2010.

1999	=	1999	,	2000 =	$= 2^4.5^3$,	2001	=	3.23.29
2002	=	2.7.11.13	,	2003 =	= 2003	,	2004	=	2 ³ .3.167
2005	=	5.401	,	2006 =	2.17.59	,	2007	=	3 ² .223
2008	=	2 ³ .251	,	2009 =	$= 7^2.41$,	2010	=	2.3.5.67

1.2.3 **Divisibility**

Definition (1.2)[5]: Let a and b be two integers, not both zero. The largest divisor d s.t. d|a and d|b is called the **greatest common divisor** (gcd) of a and b, which is denoted by gcd(a,b).

Definition (1.3)[5]: Let a and b be two integers, not both zero. d is a common multiple of a and b, the least common multiple (lcm) of a and b, is the **smallest common multiple**, which is denoted by lcm(a,b).

Definition (1.4)[5]: Integers a and b are called **relatively prime** if gcd(a,b)=1. we say that integers $n_1,n_2,...n_k$ are relatively prime if, whenever $i\neq j$, we have $gcd(n_i,n_j)=1$, $\forall i,j, 1 \le i,j \le k$.

<u>Theorem (1.2)</u>[3]: Suppose a and b are two positive integers.

If a= $\prod_{i=1}^{k} p_i^{\alpha_i}$ and b= $\prod_{i=1}^{k} p_i^{\beta_i}$, then

$$gcd(a,b) = \prod_{i=1}^{k} p_i^{\varepsilon_i}, \text{ where } \varepsilon_i = \min(\alpha_i,\beta_i), \forall i, 1 \le i \le k.$$
$$lcm(a,b) = \prod_{i=1}^{k} p_i^{\delta_i}, \text{ where } \delta_i = \max(\alpha_i,\beta_i), \forall i, 1 \le i \le k.$$

Theorem (1.3)[4]: Suppose a and b are two positive integers.

If
$$a = \prod_{i=1}^{k} p_i^{\alpha_i}$$
 and $b = \prod_{i=1}^{k} p_i^{\beta_i}$, then
 $gcd(a,b) = \prod_{i=1}^{k} p_i^{\varepsilon_i}$, where $\varepsilon_i = min(\alpha_i,\beta_i)$, $\forall i, 1 \le i \le k$.
 $lcm(a,b) = \prod_{i=1}^{k} p_i^{\delta_i}$, where $\delta_i = max(\alpha_i,\beta_i)$, $\forall i, 1 \le i \le k$.

<u>Theorem (1.4)</u> [3]: Suppose a and b are two positive integers, then:

$$\operatorname{lcm}(a,b) = \frac{a.b}{\operatorname{gcd}(a,b)}.$$

Example (1.2): Since the prime factorization of 240 and 560 are:

 $240=2^4.3.5$ and $560=2^4.5.7$, then the:

 $gcd(240,560)=2^{min(4,4)}.3^{min(1,0)}.5^{min(1,1)}.7^{min(0,1)}=2^{4}.3^{0}.5^{1}.7^{0}=80.$

 $lcm(240,560) = 2^{\max(4,4)} \cdot 3^{\max(1,0)} \cdot 5^{\max(1,1)} \cdot 7^{\max(0,1)} = 2^4 \cdot 3^1 \cdot 5^1 \cdot 7^1 = 1680.$

1.3 Arithmetic Functions [6]

Arithmetic (or number theoretic) functions are the most fundamental functions in mathematics and computer science; for example, the computable functions studied in mathematical logic and computer science are actually arithmetic functions. In this section we shall study some basic arithmetic functions that are useful in number theory. **Definition** (1.5) [7]: A function f is a rule that assigns to each element in a set D (called **Domain** of f) one and only one element in a set B. the set of images called the **range** (R) of f.

Definition(1.6)[8]: **Inverse of function** it's a relation form set Y (Codomain) to set D (Domain), such that.

 $f^{-1}: Y \rightarrow D$

Where f is function on a set D to set Y; let $b \in Y$ the inverse of b denoted by $f^{-1}(b)$ consist of these elements in D which mapped onto b, such that. $f^{-1}(b) = [x \in D, f(x) = b].$

Definition(1.7)[9]: Linear and Non-linear Function

algebraically: any polynomial with highest degree equal to one (f(x) = mx + n), where m and n are constant it's a linear function, Otherwise it's a non-linear function.

Definition (1.8): [7] A function f is called an **arithmetic function** or a **number theoretic** function if it assigns to each positive integer n a unique real or complex number f(n). Typically, an arithmetic function is a real-valued function whose domain is the set of positive integer.

Example (1.3): the equation \sqrt{n} , $n \in N$, defines an arithmetic function f which assigns the real number \sqrt{n} to each positive integer.

1.4 Prime Number

Definition (1.9) [10]: An integer **p** is called a **Prime Number** if **p** greater than one and if the only positive dividing **p** are one and **p**.

Example (1.4): 2, 3, 5, 7 ..., 31, ..., 41, 43, ..., 61, ..., 67, ...

Definition (1.10) [11]: (The Fundamental Theorem of Arithmetic) any integer positive number **n** greater than one can be written uniquely in the flowing prime factorization, $\mathbf{n} = \mathbf{p}_1^{\alpha_1} \cdot \mathbf{p}_2^{\alpha_2} \cdot \dots \cdot \mathbf{p}_k^{\alpha_k}$,

where $p_1 < p_2 < ... < p_k$, are prime numbers, $\alpha_1, \alpha_2 ... \alpha_k$ are positive integer numbers.

1.5 Modular

Definition (1.11) [12]: divisor

any non-zero integer number b satisfying the property

 $a = b \bullet m; (a, b, m \in Z^+)$

And **b** divided **a** with no remainder then **b** called divisor or factor of **a** and denoted by **b**la.

Example (1.5): 1,2,3,4,6,8,12,24 are factors of 24.

Definition (1.12) [13]: Modular Arithmetic

The **modular arithmetic** is a system of arithmetic for integers uses a finite number values, where the values "warp around" until reaching to a certain value the modulus.

 $a + b \mod n \equiv [a \mod n + b \mod n] \mod n.$

Definition (1.13) [14]: Greatest Common Divisor (G.C.D)

For any two positive integer numbers (a, b) the greatest common divisor (G.C.D) of them is the greatest number (d) that divisor of a and b (dla and dlb)

Definition (1.14) [14]: Smallest Common Multiple (L.C.M)

The Smallest common Multiple (L.C.M) of a and b, is the smallest integer c, That alc and blc.

Remark (1.2): if G. C. D (a, b) = 1 then a, b are called relatively prime. <u>Theorem (1.5)</u> [13] suppose a and b are two positive integer numbers if $a = \prod_{i=1}^{k} p_i \alpha_i$ and $b = \prod_{i=1}^{k} p_i \beta_i$ then G. C. D (a, b) = $\prod_{i=1}^{k} p_i \gamma_i$ Where $\gamma_i = \min(\alpha_i, \beta_i)$ for every i such that $1 \le i \le k$ L. C. M (a, b) = $\prod_{i=1}^{k} p_i \mu_i$ Where $\mu_i = \max(\alpha_i, \beta_i)$ for every i such that $1 \le i \le k$

Where p_i are prime numbers and α_i , β_i are non-negative numbers.

Example(1.6): G. C. D (240,560) = 80,and L. C. M (240,560) = 1680 240 = $2^4 * 3 * 5$ and $560 = 2^4 * 5 * 7$ According to theorem (1.5) G. C. D (240,560)= $2 \cdot \min(4.4) \cdot 3 \min(1.0) \cdot 5 \min(1.1) \cdot 7 \min(1.0)$ = $2^4 \cdot 3^0 \cdot 5^1 \cdot 7^0$ = 80 L. C. M (240,560) = $2^{\max(4,4)} \cdot 3^{\max(1,0)} \cdot 5^{\max(1,1)} \cdot 7^{\max(1,0)}$ = $2 \cdot 4^4 \cdot 3^1 \cdot 5^1 \cdot 7^1$

= 1680.

1.6 Group Theory [15, 16]

Definition (1.15):

1. $Z_{>a}$ is the set of positive integers greater than a:

 $Z_{>a} = \{a + 1, a + 2, \dots\}.$

2. The set of all residue classes modulo a positive integer denoted by Z_n :

 $Z_n = \{0, 1, 2, \dots, n-1\}.$

Definition (1.16): Binary Operation

A binary operation * on a set A is a rule that assign to each ordered pair (a,b) of elements of A a unique element of A.

Example (1.7): Ordinary addition + and multiplication • are binary operations on N, Z, R, or C.

Definition (1.17): Group

A **group**, denoted by $\langle G, * \rangle$ (or (G,*)), or simply G, is a G $\neq \phi$ of elements together with a binary operation *, s.t. the following axioms are satisfied:

- 1. Closure: $a*b \in G$, $\forall a, b \in G$.
- 2. Associativity: $(a*b)*c=a*(b*c), \forall a,b,c \in G$.
- Existence of identity: ∃! element e∈G, called the identity, s.t.
 e*a=a*e=a, ∀a∈G.
- 4. **Existence of inverse**: $\forall a \in G, \exists ! \text{ Element } b \in G, s.t.$

a*b=b*a=e. This b is denoted by a^{-1} and called the **inverse** of a.

The group $\langle G, * \rangle$ is called **commutative** (**abelian**) group if it satisfies further axiom:

5. Commutatively: a*b=b*a, $\forall a,b\in G$.

Example (1.8): the set Z^+ with operation + is not group (\exists no identity element), and it's not group with operation • (\exists no inverse element in Z^+).

Definition (1.18): Additive and Multiplicative Group

- If the binary operation of a group is +, then the identity of group is 0 and the inverse of a∈G is –a; this said to be an **additive group**.
- If the binary operation of a group is •, then the identity of a group is
 1 or e, this group is said to be **multiplicative group**.

Definition (1.19): Finite Group

A group is called a finite group if it has finite number of elements; otherwise it is called an infinite group.

Definition (1.20): The **order** of the group G, denoted by |G| (or by #(G)) is the number of elements of G.

Example (1.9): the order of Z is $|Z| = \infty$.

Definition (1.21): Subgroup

Let $a \in G$, where G is multiplicative group. The elements a^r , where r is an integer, form a subgroup of G, called the subgroup generated by a.

Definition (1.22): Cyclic Group

A group G is **cyclic** if $\exists a \in G$ s.t. the subgroup generated by a is the whole of G.

If G is a finite cyclic group with identity element e, the set of elements G may be written $\{e,a,a^2,...,a^{n-1}\}$, where $a^n=e$ and n is the smallest such positive integer.

Definition (1.23)[17]: Field

A field by $\langle F, \oplus, \otimes \rangle$ (or (F, \oplus, \otimes)) or simply F, is abelian group w.r.t. addition, and F-{0} is abelian w.r.t. to multiplication.

Definition (1.24)[17]: Finite Field

A finite field is a field that has a finite number of elements in it; we call the number the order of the field.

Theorem (1.6)[17]: Prime Power

 \exists a field of order q iff q is prime power (i.e. $q=p^r$) with p prime and $r \in N$.

Remark (1.3)[17]: Galois field

A field of order q with q prime power is called Galois field and is denoted by GF(q) or just F_q .

Example (1.7)[4]: The finite field F_5 has elements {0,1,2,3,4} and is described by the table(1.1) addition and multiplication table.

Table (1.1) The addition and multiplication for F_5 .

⊕	0	1	2	3	4
0	0	1	2	3	4
1	1	2	3	4	0
2	2	3	4	0	1
3	3	4	0	1	2
4	4	0	1	2	3

8	1	2	3	4
1	1	2	3	4
2	2	4	1	3
3	3	1	4	2
4	4	3	2	1

1.7 Boolean Ring and Boolean Algebra

Definition (1.25)[18]: Let $A \neq \varphi$ be a set, f be a binary operation on a set A (f:A×A→A), we call the pair (A,f) as **mathematical system**.

Definition (1.26) [18]: Let X be the universal set, and let A and B be two subsets of X, then:

- 1. The operation + defined as $A+b=A \cup B$.
- 2. The operation \oplus defined on the power P(X) set of X by:

 $A \oplus B = (A-B) \bigcup (B-A)$ s.t. $A-B = A \bigcap B'$, B' is the **complement** set of B.

The operation \oplus called Exclusive-OR (XOR) (or the symmetric difference).

3. The operation • defined as $A \cdot B = A \cap B$.

Definition (1.27) [18]: Boolean Ring

Let $(R,+,\bullet)$ be a ring with identity element, if the **Idempotency law** be satisfied $a^2=a$, $\forall a \in R$, then the ring called **Boolean ring**.

Example (1.8): Let P(X) represents the set of all the subsets of the universal set X, then the ring $(P(X), \oplus, \bullet)$ is Boolean ring.

Definition (1.28) [18]: In Boolean ring (B, \oplus, \bullet) , we defined:

- 1. **Complement**: $\overline{a}=a\oplus 1$, $\forall a \in B$.
- 2. Sum (OR): $a+b=a\oplus b\oplus a.b \forall a,b\in B$.

Definition (1.29) [18]: Boolean Algebra

The Boolean algebra is the mathematical system (B, \lor, \land) where $B \neq \varphi$, and the binary operations \lor and \land defined on B as follows:

- 1. The operations \lor and \land are commutative.
- 2. The operations \lor and \land are satisfy the distribution law for each to other.
- 3. \exists two identity distinct elements 0 and 1 of the operations \lor and \land respectively s.t. $a\lor 0=a$ and $a\land 1=a$, $\forall a\in B$.

Example (1.9): The system (P(X), \bigcup , \bigcap) is boolean algebra, $X \neq \varphi$, we use $\varphi=0$ and X=1. If B be a set of subsets of X including φ and X which is closed on \bigcup and complement then (B, \bigcup , \bigcap) is boolean algebra too.

<u>Theorem (1.7)</u>[19]: Every boolean algebra (B, \lor, \land) is boolean ring (B, \oplus, \bullet) when we defined the operations \oplus and \bullet as follows:

- 1. $a \oplus b = (a \land b') \lor (a' \land b)$.
- 2. a•b=a∧b.
- ∀a,b∈B.

<u>**Theorem (1.8)</u>** [19]: Every ring (B, \oplus, \bullet) is Boolean algebra (B, \lor, \land) when we defined \lor and \land as follows: $\forall a, b \in B$.</u>

- 1. $a \lor b = a \oplus b \oplus a \bullet b$.
- 2. a∧b=a•b.

<u>Theorem (1.9)</u>[19]: The ring $(Z_p, \oplus, \bigotimes)$ is field iff p is prime number s.t.

 $a \oplus b = a + b \pmod{p}$.

 $a \otimes b = a \cdot b \pmod{p}$.

This field is Galois field and is denoted by GF(p), $\forall a, b \in Z_p$.

1.8 Logic Circuits[19]

In electronically logical circuits (which are subject to the Boolean algebra), there are small circuits called Gates which are, for example, part from transistors, diodes, capacitors, and etc, these gates are shown in figure (1.1):



Figure (1.1) The boolean gates.

(a). The gate AND: is multiplying the input variables.

(b). The gate OR: summing the input variables.

(c).The gate NOT: complement of the input variable.

(d). The gate XOR: summing XOR the input variables.

These gates are shown in the table (1-2).

•	0	1	+	0	1	A	a	\oplus	0	1
0	0	0	0	0	1	0	1	0	0	1
1	0	1	1	1	1	1	0	1	1	0

Table (1.2) The truth tables of the four gates.

Definition (1.30): The logical function f is called the **output function** defined $f:B^n \rightarrow B$, where B^n is a set of n input binary data, f subject to the Boolean algebra laws and we can apply the gates concepts on it, s.t. $x=f \cdot g$, y=f+g, z=f, and $w=f \oplus g$, where f and g are Boolean functions.

1.9 Sequences and Series [20]

1.9.1 Sequences

Definition (1.31): Sequence

The sequence in the field F is a function *f*, whose domain is the set of non-negative (or could be positive) integer, s.t. $f : \mathbb{Z} \to \mathbb{F}$, and its denoted by $S = \{S_n\}_{n=0}^{+\infty}$.

Definition (1.32): The Sequence S is **periodic** when $\exists p \in Z^+$ s.t. $s_0=s_p, s_1=s_{p+1}, \ldots$, the minimum p is the **period** of S.

If $Z_m = \{0, 1, ..., m-1\}$, where $m \in Z^+$, then S is digital sequence. In special case, if m=2 then S is binary sequence, and if m=3 then S is tri sequence.

1.9.2 Series

Definition (1.33): An infinite series is an expression of the form:

$$u_1 + u_2 + \ldots + \ldots = \sum_{k=1}^{\infty} u_k$$

Let S_n denotes the sum of the first n terms of the series s.t.

$$S_n = \sum_{k=1}^n u_k$$
, and $\{S_n\}_{n=1}^{+\infty}$ is called the sequence of partial sums.

 $S = \sum_{k=1}^{\infty} u_k$ is called the **sum** of the series.

Theorem(1.10): A geometric series $a+ar+ar^2+...+ar^{k-1}+...(a\neq 0)$ is converges if |r|<1 and the sum is $\frac{a}{1-r}=a+ar+ar^2+...+ar^{k-1}+...$, and diverges if $|r|\geq 1$.

1.10 Literature Survey

While there are have been many papers written on PSO and their application to various problems, there are relatively few papers that apply PSO to cryptanalysis.

In 1995, Kennedy J. and Eberhart R. introduced a concept for the optimization of nonlinear functions using particle swarm methodology. The evolution of several paradigms outlined, and an implementation of one of the paradigms had been discussed. Kennedy and Eberhart proposed Benchmark testing of the paradigm which describes the applications including nonlinear function optimization and neural network training. The described relationship is between particle swarm optimization and both artificial life and genetic algorithms [21].

In 1999 Eberhart R.C. and Hu X. arranged a new method for the analysis of human tremor using particle swarm optimization which is used to evolve a neural network that distinguishes between normal subject and those with tremor. Inputs to the neural network are normalized movement amplitudes obtained from an actigraph system. The results from this preliminary investigation are quite promising, and the work is continuing [22].

In 2002, Venter G. and Sobieszczanski J. demonstrated the application of Particle Swarm Optimization to a realistic Multidisciplinary Optimization test problem. A new contribution to multidisciplinary optimization is the application of a new algorithm for dealing with the unique challenges associated with multidisciplinary optimization problems [23].

In 2002, Parsopoulos K. E. and Vrahatis M. N. adopted a new method PSO technique for the alleviation of local minima, and for detecting multiple minimizers are also described. Moreover, results on the ability of the PSO in tackling Multiobjective, Minimax and Integer Programming, as well as problems in noisy and continuously changing environments, are reported. Finally, a Composite PSO, in which the heuristic parameters of PSO are controlled by a Differential Evolution algorithm during the optimization that is described, and results for many well-known and widely used test functions are given [24].

In 2003, Rahmat-Samii Y., Gies D., and Robinson J. are adopted a conceptual overview of the algorithm, keeping at all times the focus on implementing Particle Swarm Optimization to solve practical problems. In this vein, a selection of recent applications of the method to real-world design examples will also be presented [25].

On 2^{nd} February 2003, Bliss L. adopted a new method which extends ANN training to include topological optimization of the network, especially the reduction of the number of inputs to the ANN [26].

On 6th may 2003, much work has been done by Bliss L. in the area of configuring ANN topology automatically using soft computing techniques such as GA. However, little time has been spent by researches on selecting the proper inputs to the ANN. NN used to predict the behavior of dynamical systems often have a choice of input information, much of which is redundant. Selecting a minimal set of inputs that produce acceptable behavior results in a lower cost solution. Researchers using trial and error methods currently do this input selection manually. The work shows several methods of automatically selecting a small set of inputs from a large candidate population. PSO is the primary network optimization technique used for processing ANN configuration [27].

In February 2004, Shi Y. surveyed the research and development of PSO in five categories: algorithms, topology, parameters, hybrid PSO algorithms, and applications. There are certainly other research works on PSO which are not included due to the space limitation. In general, the search process of a PSO algorithm should be a process consisted of both contraction and expansion so that it could have the ability to escape from local minima, and eventually find good enough solutions. A mathematical foundation of PSO needs to have a deep understanding of the dynamic process of PSO. There is also a need for a unique representation of the PSO topology and a need for a standard set of benchmark functions so that researchers can duplicate each other's work and compare their work with the others [28].

There are more literatures survey will be discussed in details chapter three.

1.11 Objective of Thesis

The objective of this thesis is to investigate and evaluate one of the searching methods called Particle Swarm Optimization (PSO) and how

this algorithm can be implemented. The main goal of this thesis is to attack the stream cipher systems, specifically. The cryptanalysis issue includes attack the non-linear equations system and the output key sequence (which is known to the cryptanalyst) to retrieve the initial key values of LFSR(s) which generate this sequence. We propose a PSO cryptanalysis system to find the initial key of each LFSR which consists of particularized for construction the mathematical representation of nonlinear equation systems of each cryptosystem.

1.12 Thesis Outlines

The solution of our problem has been covered through five chapters, the first three chapters are considered to provide the main concepts of this thesis, while the proposed system, practical work and the obtained results are explained in chapter four. Finally we introduced the conclusions and future work in the chapter five.

- **Chapter Two:** deals with cryptology, classical cryptosystem types (simple substitution cipher and simple transposition cipher, cryptanalysis and cryptanalytic tools for classical cryptosystems. And shows the importance of stream cipher system and its classification, then showing some classical and modern cryptanalysis methods. Lastly, we will illustrate the types of attack.
- Chapter Three: Presents the background of swarm intelligence and its applications, the background of PSO algorithm, biological collective behavior, and its applications.And the differences between PSO and classical methods.The operators and parameters of PSO are detailed in this chapter. In addition, the most application fields of PSO.

Chapter Four: covers the use of PSO algorithm as a cryptanalysis tool to attack such classical cryptosystems, and shows the experimental results for the implementation of the basic algorithm. We introduce how we can put the output results for each cryptosystem as a nonlinear equations system then put a new method to attack this systems depending on PSO.

Chapter Five: This chapter includes a conclusions and future work.



Chapter TWO Cryptography and Stream Cipher Systems

2.1 Introduction

Cryptography means hidden writing, the practice of using encryption to conceal text. A **Cryptanalyst** studies encryption and encrypted messages, with the goal of finding the hidden meanings of the messages. Both a cryptographer and a cryptanalyst attempt to translate coded material to its original form; normally a cryptographer works on behalf of a legitimate sender or receiver, while a cryptanalyst works on behalf of an unauthorized interceptor. Finally, **Cryptology** is the research into and study of encryption and decryption; it includes both cryptography and cryptanalysis [1].

This chapter introduces a description for the most important terminology in cryptography and some important known stream cipher systems which are depend on linear feedback shift register which are considered as a basic unit of stream cipher systems.

2.2 <u>Terminology</u>

Cryptography (from the Greek Kryptós, "**hidden**" and gráphein, "**to write**") is the study of principles and techniques by which information can be concealed in ciphertexts and later revealed by legitimates users employing the secret key, but in which it is either impossible or computationally infeasible for an unauthorized person to do so. **Cryptanalysis** (from the Greek Kryptós, and analyéin "**to loosen**") is the science (and art) of recovering information from ciphertexts without knowledge of the key. Both terms are subordinate to the more general term **Cryptology** (from the Greek Kryptós, and logos, "**word**"). The cryptography concerned in **Encryption** and **Decryption** processes [1]. Now we have to present some important notations:

- Message space M: a set of strings (plaintext messages) over some alphabet, that needs to be encrypted.
- **Ciphertext space** C: a set of strings (ciphertexts) over some alphabet that has been encrypted.
- **Key space** K: a set of strings (keys) over some alphabet, which includes the encryption key e_k and the decryption key d_k.
- The **Encryption** process (algorithm) E: $Ee_k(M)=C$.
- The **Decryption** process (algorithm) D: Dd_k(C)=M.

The algorithms E and D must have the property that:

 $Dd_k(C)=Dd_k(Ee_k(M))=M.$

The above situations shown in figure (2.1).



Figure (2.1) Encryption Process.

2.3 Cryptosystems

The **Cryptosystem** are the systems which use the encryption and decryption processes, these systems can be classified as in figure (2.2).

Whenever **Cryptanalysis** is the science and study of methods of breaking ciphers. It is a system identification problem, and the goal of **Cryptography** is to build systems that are hard to identify [2]. To attack a cryptographic system successfully the cryptanalysis is forced to be based on subtle approaches, such as knowledge of at least part of the text encrypted, knowledge of characteristic features of the language used,..., with some

luck. However, in practice, some of this information may be inaccurate, imprecise, or missing, which, in turn, causes to decrease the possibility of attacking and increasing the time or the resources required by the analyst.



Figure (2.2) Cryptosystems classification

There are essentially two different types of cryptographic systems (cryptosystems), these cryptosystems are described in the next two subsections. [3]

2.3.1 Public Key Cryptographic System

It is also called **asymmetric cryptosystems**. In a public key (**non-secret key**) cryptosystem (see figure (2.3)), the encryption key e_k and decryption key d_k are different, that is $e_k \neq d_k$.



Figure (2.3) Modern public-key cryptosystem, $e_k \neq d_{k.}$

2.3.2 Secret Key Cryptographic System

It's also called **symmetric cryptosystems**. In a conventional secret-key cryptosystem (see figure (2.4)), the same key $(e_k=d_k=k\in K)$, called **secret key**, used in both encryption and decryption; we are interest in this type of cryptosystems.



Figure (2.4) Conventional secret-key cryptosystems
The sender uses an invertible transformation f defined by:

$$f: \mathbf{M} \longrightarrow \mathbf{C}$$

So produce the ciphertext:

 $c=(E_k(m)), m \in M \text{ and } c \in C.$

and transmits it over the public insecure channel to the receiver. The key k should also be transmitted to the legitimate receiver for decryption but via a secure channel since the legitimate receiver knows the key k, he can decrypt c by transformation f^{-1} defined by:

$$f^{-1}: \mathbf{C} \longrightarrow \mathbf{M}$$

and obtain:

 $D_k(c)=D_k(E_k(m))=m, c\in C \text{ and } m\in M,$

and it's the original plaintext message.

There are many different types of secret key cryptosystems. In what follows, we shall introduce some of these systems. [4]

I. Stream (Bit) Ciphers

This kind of secret key cryptosystems is our interest, so we will detail it in the next section.

II. Monographic (Character) Ciphers

Earlier ciphers (cryptosystems) were based on transforming each letter of the plaintext into a different letter to produce the ciphertext. Such ciphers are called **character substitution or monographic ciphers**, since each letter is shifted individually to another letter by a substitution.

III. Polygraphic (Block) Ciphers

Monographic ciphers can be made more secure by splitting the plaintext into groups of letters (rather than a signal letter) and then performing the encryption and decryption on these groups of letters.

This block technique is called **block ciphering**. Block cipher is also called a **polygraphic cipher**.

2.4 Linear Feedback Shift Register

A feedback shift register is made up of two parts: a shift register and a feedback function (see figure (2.5)). The shift register is a sequence of bits, (the length of a shift register is figured in bits). Each time a bit is needed, all of the bits in the shift register are shifted 1 bit to the right. The new left-most bit is computed as a function of the other bits in the register. The output of the shift register is 1 bit, often the least significant bit. The period of a shift register is the length of the output sequence before it starts repeating.



Figure (2.5) Feedback Shift Register.

Cryptographers have liked stream ciphers made up of shift registers: They are easily implemented in digital hardware. We will only touch on the mathematical theory.

Ernst Selmer, the Norwegian governments' chief cryptographer, worked out the theory of shift register sequences in 1965 [5]. Solomon Golomb, an NSA mathematician, wrote a book with Selmers results and some of his own [6].

The simplest kind of feedback shift register is a Linear Feedback Shift Register (LFSR), as described in figure (2.6). The feedback function is simply the XOR of certain bits in the register; the list of these bits is called a **tap sequence**. Because of the simple feedback sequence, a large body of mathematical theory can be applied to analyzing LFSRs. Cryptographers like to analyze sequences to convince themselves that they are random enough to be secure. LFSR's are the most common type of shift registers used in cryptography.



Figure (2.6) Linear Feedback Shift Register.

In order for a particular LFSR to be a maximal-period LFSR, the polynomial formed from a tap sequence plus the constant 1 must be a primitive polynomial mod 2. The degree of the polynomial is the length of the shift register. A primitive polynomial of degree n is an irreducible polynomial.

Linear feedback shift registers (LFSRs) are used in many of the keystream generators that have been proposed in the literature. There are several reasons for this [7]:

- 1. LFSRs are well-suited to hardware implementation.
- 2. They can produce sequences of large period.
- 3. They can produce sequences with good statistical properties.
- 4. Because of their structure, they can be readily analyzed using algebraic techniques.

A linear feedback shift register (LFSR) of length L consists of L stages (or delay elements) numbered 0,1,...,L-1, each capable of storing one bit and having one input and one output; and a clock which controls the movement of data. During each unit of time the following operations are performed:

- 1. The content of stage 0 is output and forms part of the output sequence.
- 2. The content of stage i is moved to stage i-1 for each i, $1 \le i \le L-1$.
- The new content of stage L-1 is the feedback bit sj which is calculated by adding together modulo 2 the previous contents of a fixed subset of stages 0,1,...,L-1.

Every output sequence (i.e., for all possible initial states) of an LFSR (L,C(D)) is periodic if and only if the connection polynomial C(D) has degree L.

If $C(D) \in Z_2[D]$ is a primitive polynomial of degree L, then $\langle L, C(D) \rangle$ is called a **maximum-length LFSR**. The output of a maximum-length LFSR with non-zero initial state is called an **m-sequence**.

The basic approach to designing a keystream generator using LFSR is simple. First you take one or more LFSR, generally of different lengths and with different feedback polynomials. (If the lengths are all relatively prime and the feedback polynomials are all primitive, the whole generator is **maximal** length). The key is the initial state of the LFSR. Every time you want a bit, **shift** the LFSR once (this is sometimes called clocking). The output bit is a function, preferably a nonlinear function, of some of the bits of the LFSR. This function is called the **combining function**, and the whole generator is called a combination generator.

Three general methodologies for destroying the linearity properties of LFSRs are discussed in this section [7]:

1. Using a nonlinear combining function on the outputs of several LFSRs.

- 2. Using a nonlinear filtering function on the contents of a single LFSR.
- 3. Using the output of one (or more) LFSRs to control the clock of one (or more) other LFSRs

2.5 <u>Stream Cipher Systems</u>

In **stream ciphers**, the message units are bits, and the key is usual produced by a **random bit generator** (see figure (2.7)). The plaintext is encrypted on a bit-by-bit basis.



Figure (2.7) A stream (Bit) cipher.

The key is fed into random bit generator to create a long sequence of binary signals. This "key-stream" k is then mixed with plaintext m, usually by a bit wise XOR (Exclusive-OR modulo 2 addition) to produce the ciphertext stream, using the same random bit generator and seed.

Stream ciphers are an important class of encryption algorithms. They encrypt individual characters (usually binary digits) of a plaintext message one at a time, using an encryption transformation which varies with time. By contrast, block ciphers tend to simultaneously encrypt groups of characters of a plaintext message using a fixed encryption transformation. Stream ciphers are generally faster than block ciphers in hardware, and have less complex hardware circuitry. They are also more appropriate, mandatory and in some cases (e.g., in some

telecommunications applications), when buffering is limited or when characters must be individually processed as they are received. Because they have limited or no error propagation, stream ciphers may also be advantageous in situations where transmission errors are highly probable.

There is a vast body of theoretical knowledge on stream ciphers, and various design principles for stream ciphers have been proposed and extensively analyzed. However, there are relatively few fully-specified stream cipher algorithms in the open literature. This unfortunate state of affairs can partially be explained by the fact that most stream ciphers used in practice tend to be proprietary and confidential. By contrast, numerous concrete block cipher proposals have been published, some of which have been standardized or placed in the public domain. Nevertheless, because of their significant advantages, stream ciphers are widely used today, and one can expect increasingly more concrete proposals in the coming years.[8]

2.6 Combination Generator

One approach is to use n LFSRs in parallel; their outputs combined using an n-input binary **Boolean function** or **combining function** (CF). Figure (2.8) shows the design of n-LFSR's generator with combining function.[9]

Because LFSRs are inherently linear, one technique for removing the linearity is to feed the outputs of several parallel LFSRs into a non-linear Boolean function to form a **combination generator**. Various properties of such a combining function are critical for ensuring the security of the resultant scheme, for example, in order to avoid correlation attacks.[10]

Since a well-designed system should be secure against known plaintext attacks, an LFSR should never be used by itself as a keystream generator. Nevertheless, LFSRs are desirable because of their very low implementation costs.[11] For essentially all possible secret keys, the output sequence of an LFSR based keystream generator should have the following properties:

1. large period.

2. large linear complexity.

3. good statistical properties.

It is emphasized that these properties are only **necessary** conditions for a keystream generator to be considered cryptographically secure. Since mathematical proofs of security of such generators are not known, such generators can only be deemed **computationally secure** after having withstood sufficient public scrutiny. [7]

The LFSRs in an LFSR-based keystream generator may have known or secret connection polynomials. For known connections, the secret key generally consists of the initial contents of the component LFSRs. For secret connections, the secret key for the keystream generator generally consists of both the initial contents and the connections.



Figure (2.8) n-LFSR's Generator with Combining Function

2.7 Examples of Known Generators

Some examples of known keystream generators are introduced.

2.7.1 Linear Generator [12]

The **Linear generator**, illustrated in figure (2.9), is defined by nmaximum-length LFSRs whose lengths $r_1, r_2, ..., r_n$, where $n \in Z^+$ are pair wise relatively prime, with XOR combining function:

$$F(x_1, x_2, \dots, x_n) = x_1 \oplus x_2 \oplus \dots \oplus x_n \qquad \dots (2.1)$$

This generator considered weak, despite of his good randomness, because of his weak linear complexity.



Figure (2.9) n-Linear Generator.

2.7.2 Product Generator [12]

The **Product generator**, illustrated in figure (2.10), is defined by n-maximum-length LFSRs whose lengths $r_1, r_2, ..., r_n$, where $n \in Z^+$ are pair wise relatively prime, with AND combining function:

$$F(x_1, x_2, ..., x_n) = x_1 \bullet x_2 \bullet ... \bullet x_n = \prod_{i=1}^n x_i \qquad ... (2.2)$$

This generator considered weak, despite of his good linear complexity, because of his weak randomness.



Figure (2.10) n-Product Generator.

2.7.3 Threshold Generator [13]

This generator as usual using combining function called Majority function which is balance and symmetric (which expect that this generator will produces pseudo random generator). This generator illustrated in figure (2.11) tries to get around the security problems by using a variable number of LFSR's. The theory is that if you use a lot of LFSRs, it's harder to break the cipher.



Figure (2.11) Threshold generator

Take the output of a large number of LFSRs (use an odd number of them). Make sure the lengths of all the LFSRs are relatively prime and all the feedback polynomials are primitive: maximize the period. If more

than half the output bits are 1, then the output of the generator is 1. If more than half the output bits are 0, then the output of the generator is 0.

With three LFSRs, the output generator can be written as:

The Threshold generator using the non-linear combining function s.t:

 $F_3(x_1,x_2,x_3) = x_1x_2 \oplus x_1x_3 \oplus x_2x_3.$

From the combing function of this generator, we expect that it has a larger linear complexity (LC): [12]

$$LC(S) = r_1r_2 + r_1r_3 + r_2r_3$$

where r_1 , r_2 , and r_3 are the lengths of the first, second, and third LFSRs.

2.8 Cryptanalysis

Cryptanalysis plays an essential role in the design of ciphers. A good cipher should be designed by taking into account all the known cryptanalysis techniques and the designer's insight into unknown attacks. For example, DES would not have been designed in the same way if the differential attack had not been invented at that time, and AES would not give adequate security margin if the square attack had not been developed at that time. In the following, we illustrate some general attacks on stream ciphers, followed by the dedicated attacks on LFSR based stream ciphers. The countermeasure against these attacks will be discussed.[14]

Unlike designing a cipher system, breaking a cipher system sometimes highly depends on guess and luck. Whatever method of cryptanalysis is used, the analyst must always expend some amount of time and resources (defined as work factor) to reach his goal. By increasing available resources, the time required to attack the cipher successfully can often be reduced. Consequently, there is a relationship between cost and time for any given cryptanalytic attack against a cipher. Also, there is a relationship established between the value, of the information obtained by breaking a cipher, and time. These two relationships can be used to determine the practical secrecy of the cipher. Usually, cryptanalysis involves high-speed computers, and complex, sophisticated computer programs. This includes: first, computer processors, which may include special purpose hardware to execute the logical and arithmetic operations needed to obtain the solution, second, computer storage for the analysis programs and its data, and third human resources to devise and write analysis programs, gather data, and oversee the analysis.

The basic concepts of cryptanalysis were developed as a branch of applied mathematics; the cryptanalysis uses the following tools: [15]

- 1. Probability theory and statistics.
- 2. Linear algebra.
- 3. Abstract algebra (group theory).
- 4. Complexity theory.

2.9 Attacking of Stream Cipher Methods

The attacking methods of stream cipher could be classified as displayed in Figure (2.12).



Figure (2.12) Attacking methods of Stream Cipher.

The classification is based on the information processing approaches and the tools that are utilized by the cryptanalysis. From figure (2.12), clearly the classification has two major parts: classical methods, and modern methods. The classical methods include the most efficient methods used for attacking the stream cipher, but they are not the only methods in this area; they are: matrix method, Massey algorithm, and correlation methods (including fast correlation). These methods usually may use some or all cryptanalysis requirements and tools given in next sections. However, the modern methods depend on different approaches for information processing, namely biological like processing. We classify them as modern methods since they depend on new tools, which are:

- 1. Genetic Algorithms. [16]
- 2. Neural Networks. [17]

These new tools can greatly facilitate cryptanalysis, as we shall explain in this chapter. In fact, the variety of new technologies increases the possibilities of attack. So that, each major advance in information technology must change our ideas about data security [18]. The requirements summed up by the phrase "data security" do not stay the same; they change rapidly as the technology changes. One of the reasons for the speed of development in cryptography is, of course, the presence of cryptanalyst. [19]

2.9.1 <u>Classical Cryptanalysis Methods</u>

Although there is a considerable literature on the design of cryptography system, relatively little public domain information exists on techniques for cryptanalysis. In this section we present an overview of the most efficient methods used to attack stream cipher (linear and non-linear type):

I. Matrix Method

Meyer et al [20,21], have demonstrated a method of breaking an "N-stage" LFSR given (2N) consecutive bits of known plaintext. The basic method is to set up the matrix equation: K = MC

$$\begin{bmatrix} \mathbf{K}_{n+1} \\ \mathbf{K}_{n+2} \\ \mathbf{K}_{n+3} \\ \vdots \\ \mathbf{K}_{2n} \end{bmatrix} = \begin{bmatrix} \mathbf{M}_{n} & \mathbf{M}_{n-1} & \mathbf{M}_{n-2} & \cdots & \mathbf{M}_{1} \\ \mathbf{0} & \mathbf{M}_{n} & \mathbf{M}_{n-1} & \cdots & \mathbf{M}_{2} \\ \mathbf{0} & \mathbf{0} & \mathbf{M}_{n} & \cdots & \mathbf{M}_{3} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \cdots & \mathbf{M}_{n} \end{bmatrix} \begin{bmatrix} \mathbf{C}_{1} \\ \mathbf{C}_{2} \\ \mathbf{C}_{3} \\ \vdots \\ \mathbf{C}_{n} \end{bmatrix}$$

where

M : is the matrix of successive shifts of the first n bits of plaintext.

C : is the unknown matrix of switch states.

K. : is the key matrix.

Thus the switch values can be obtained by inverting M and solving:

 $C = M^{-1} K$

Therefore, the entire key will be known completely. Although finding the inverse of matrix is not trivial (the time taken to find the inverse matrix over GF(2) is proportional to $O(N^3)$, it is a straightforward process. But this method is weak, since if less than 2N consecutive bits are known this may not be enough to determine the entire sequence.

Beker and Piper [19], showed two methods of breaking an "Nstage" LFSR given (2N) bits of the known plaintext sequence where the bits are not necessarily consecutive. These methods are based on trying every possibility for filling unknown entries in the sequence, and for each one they merely use the techniques of the matrix equation, so that, they involve a mixture of guessing and solving simultaneous equations. The choice between these two methods is usually made by seeing which will require fewer trials.

II. Berlckamp-Massey Shift Register Synthesis Algorithm

The iterative algorithm introduced by BerleKamp [22] for decoding Bose-Chaudhuri-Hocquenghem (BCH) codes, provides efficient solution to the problem of synthesizing the shortest linear feedback shift register capable of generating a finite sequence of bits. The algorithm leads to the polynomial of smallest possible degree (N) as providing (2N) bits from shift register of length (N). [23]

III. Correlation and Fast Correlation Methods

Siegenthaler [24], in 1985, demonstrated a method that the LFSR_i part of the key can be found independently of the other LFSR_s parts, by using the "divide and conquer" technique. This method showed that the number of trials to find the key can be reduced significantly in those cases where a correlation exists between the output of the running key generator employed in a stream cipher, and LFSR_i sequence with

correlation probability P (up to 0.75). These generators have been broken for LFSR lengths (N < 50).

Meier and Staffelbach [25], in 1988, developed two algorithms (A and B), which are much faster than the above attack and are demonstrated to be successful against shift registers of considerable length N (N>>50), provided that the number t of feedback taps is small (t< 10 if $P \le 0.75$).

Both A and B algorithms are developed by using the statistical model of Siegenthaler. On the other hand, for correlation probabilities P<0.75 the attacks are proven to be infeasible against long LFSRs if they have a greater number of taps (roughly N \geq 100 and t \geq 10).

2.9.2 Modern Cryptanalysis Methods

The modern methods of cryptanalysis are based on new and different approaches to minimize the time and the cost of attacking. These methods, as displayed in figure (3.10), are directed to utilize genetic algorithms and neural network concepts.

I. Genetic Algorithms Methods

Genetic Algorithms are search algorithms based on the mechanics of natural selection and natural genetics. They use concepts drawn from the theory of evolution to "breed" progressively better solutions to problems with very large solution spaces [26]. With their ability to efficiently search huge solution spaces, genetic algorithms would seem a natural candidate for use in cryptanalysis. [27]

Spillman, et al showed the use of genetic algorithms in the cryptanalysis of simple substitution ciphers. [28]

Spillman and Rechard, used a new method to attack knapsack cipher using genetic algorithms to decrease the time for breaking. [29]

Matthews, demonstrated the use of genetic algorithms to break classical transposition ciphers by finding the transposition sequence used.

However, there are a number of cryptographic algorithms that cannot be attacked using genetic algorithms, a large number of cryptographic algorithms, including those underpinning many rotor-based systems (for example stream cipher systems), appear vulnerable to attack by genetic algorithms. [27]

II. Neural Networks Method

The general interest in the neural networks arises from their fascinating properties which enable them to exceed the limitations of traditional information processing.

Although it seems that neural network is a valuable tool for use in cryptanalysis, neural network is not a panacea. Therefore an important question must be answered: Does cryptanalysis make a suitable problem to be solved by Neural Networks? To answer, we must know the characteristics that must be exhibited by the problem to be suitable for solution by neural network. They are: [30]

- 1. The rule used in solving the problem may be unknown, or very difficult to explain or formalize.
- 2. The problem makes use of noisy, or incomplete data.
- 3. The problem may evolve.
- 4. The problem needs very high speed processing.
- 5. There may be no current technical solutions.

2.10 Adversarial Models [31]

The capabilities of an adversary in terms of operations he is able or allowed to execute, is another important factor during a cryptanalytic attack. These conditions are commonly summarized in adversarial models and are categorized by the type of data and by the type of access an adversary requires to successfully mount a given attack. The type of data differentiates between inputs and outputs of a cryptosystem such as secret keys, plaintexts, and ciphertexts, and the type of access differentiates between reading, writing and adaptive writing access, which are denoted as known values, chosen values and adaptively chosen values, respectively. An overview on the main adversarial models in conventional cryptanalysis is given below:

2.10.1 Ciphertext-only Attacks [31]

The adversary knows only the ciphertext and has no access to the plaintext. A cryptographic primitive vulnerable to such kind of attacks is considered exceptionally weak, since it is possible to distinguish it from a random permutation by analysing only ciphertexts.

2.10.2 Known-plaintext Attacks [32]

The adversary has reading access to plain- and corresponding ciphertexts processed by the cipher. A representative of this category is, for example, linear cryptanalysis.

2.10.3 Chosen-plaintext Attacks [33]

These are similar to known-plaintext attacks, with the difference that an adversary is allowed to choose the concrete plaintexts to be encrypted prior to the attack. A well-known attack type of this category is differential cryptanalysis.

2.10.4 Chosen-ciphertext Attacks [34]

The adversary can choose ciphertexts to be decrypted by the cipher before the attack starts and has reading access to the resulting plaintexts.

2.10.5 Adaptively Chosen-plaintext Attacks [34]

The adversary can select plaintexts to be encrypted during the attack and is not forced to choose them before the attack starts as in the case of the chosen plaintext scenario. The attacker also has access to the resulting ciphertexts.

2.10.6 Adaptively Chosen-ciphertext Attacks [34]

The adversary can select ciphertexts to be decrypted during the attack and is not forced to choose them before the attack starts as in the case of the chosen ciphertext scenario. The attacker also has access to the resulting plaintexts.

2.10.7 Related-key Attacks [35]

The adversary can encrypt plaintexts and decrypt ciphertexts with the attacked key and with keys related to the latter, which, for example, differ only at certain bit positions.

However, at the same time collecting data of a given type becomes more and more demanding the further we go down that list. The above categorization also presents an indication on the practicability of the attacks. The above models also form the basis for implementation attacks, however, an attacker is assumed to have additional capabilities.

2.11 Types of Attacks [36]

In this section we will present the types of attacks, we also explain and discuss what is the use of the attack.

It is important to understand that all the attacks have one purpose. The purpose is to discover the key used in the process of ciphering and deciphering. Each attack has a method to try to discover the key that was used, we will give some examples of the application of the attack.

2.11.1 Exhaustive Search Attack [37]

The exhaustive search attack is also called brute force. The method of this attack is to search through all possible states, checking for a match between the resulting and the observed keystream.

Fortunately, Babbage in 1995 improved the exhaustive search attack in stream ciphers. He defined two attacks in this area.

In the first attack, the attacker first procuces a list of n-bit subsequences, sorted in lexographic (or numberic) order. Then the attacker select a random candidate state in this list and check, if the selected state produces the output of cipher, then the attacker found the initial state else he continus try to find the initial state.

The second attack was defined by Babbage as:

"Let V be a vector space of dimension n over GF(2), with each possible KG(Keystream Generator) state an element of V. The initial state, which we wish to determine, is s_0 , and the state transition function is linear, and so can be represented by an nxn matrix A, so that $s_i = s_0A_i$. The output function h : V \rightarrow GF(2), so that the *i*th keystream bit k_i is equal to h(si)."

2.11.2 Algebraic Attack [38]

The algebraic attack is used in stream ciphers based in LFSRs. This attack try to find the initial state given some keystream bits.

The algebraic attacks has two steps. In the first step, the attack tries to find a system of equations in the bits of the secret key K and the output bits Z_t . If it has enough low degree equations and known key bits stream, then the secret key K can be recovered by solving this system of equations in a second step. This system could be solved using Groebner bases.

2.11.3 Correlation Attack [39]

The correlation attack was proposed by Siegenthaler in 1985. An important work in this area was elaborated by Meier and Staffelbach.

After them, Mihaljevi and Goli was one of the promising work. Other important work is from Anderson, he started the search for the optimum correlation attack. They opened the world of cryptanalysis to correlation attack. The correlation attack is defined as:

"The correlation attack exploits the existence of a statistical dependence between the keystream and the output of a single constituent LFSR."

2.11.4 <u>Fault Attack</u> [40]

The fault attack is a powerful cryptanalytic tool. It is widely applied in cryptosystems which are not vulnerable to direct attack. It is easy. The idea of Correlation attack involving several constituent LFSRs attacks in block ciphers, but the first application of this attack in stream cipher was developed by Hoch and Shamir.

In this attack, the attacker can apply some bit flipping faults to either the RAM or the internal register of the cryptographic device. However, he had only a partial control over their number, location and timing. This model tries to reflect a situation in which the attacker has the possession of the physical device, and the faults are transient rather than permanent.

A good work in this area was developed by Barenghi et al, they talk about this technique and where it can be applied. In their work has examples using stream ciphers and block ciphers.

2.11.5 Chosen-IV Attack [41]

In the Chosen-IV attack one of the relevant work in this area is from Joux and Muller. To understand more about this attack we should bring the definition from Joux and Muller work:

"In general, a stream cipher produces a pseudo random sequence PRNG(K, IV) from a secret key K and an initialization vector IV. Then, the ciphertext C is computed from the plaintext P by:

 $C = PRNG(K, IV) \oplus P$.

The main idea behind the use of initialization vectors is to generate different pseudorandom sequences without necessarily changing the secret key, since it is totally insecure to use twice the same sequence." Then, this attack exploits the weaknesses in the key scheduling algorithm of the stream cipher. The attack tried to extract from the memory, the initial state of the LFSR. Like the algebraic attack.

2.11.6 Slide Attack [42]

The first time that the slide attack appeared in the literature was with Biryukov and Wagner. They used the attack in TREYFER, WAKE-ROFB and others block ciphers. In 2000 they improved the slide attack and used in other block ciphers. More recently slide attacks have been applied to other stream ciphers, such as Trivium with Priemuth-Schmid and Biryukov.

The main idea of the attack is defined by Biryukov and Wagner like: "The idea is to slide one copy of the encryption process against another copy of the encryption process, so that the two processes are one round out of phase."

2.11.7 Cube Attack [43]

The cube attack is relative new. It has been introduced by Dinur and Shamir in 2009.

"The attack exploits the existence of low degree polynomial representation of a single output bit (as a function of the key and plaintext bits) in order to recover the secret key. In order to derive the secret key, the attacker sums this bit over all possible values of a subset of the plaintext bits. The summations are used in order to derive linear equations in the key bits which can be efficiently solved". This attack can be applied in almost any cryptosystem.

2.11.8 <u>Time-Memory Trade-off Attack</u> [44,45]

Biryukov and Shamir extended this attack for stream ciphers. The Time/Memory/Data Tradeoff Attack has two phases:

"During the preprocessing phase (which can take a very long time) the attacker explores the general structure of the cryptosystem, and summarizes his findings in large tables (which are not tied to particular keys). During the realtime phase, the attacker is given actual data produced from a particular unknown key, and his goal is to use the precomputed tables in order to find the key as quickly as possible." In any time-memory tradeoff attack there are five key parameters:

N: represents the size of the search space.

P: represents the time required by the preprocessing phase of the attack.

M: represents the amount of RAM (hard disks or DVDs) available to the attacker.

T: represents the time required by the realtime phase of the attack.

D: represents the amount of realtime data available to the attacker.

Verdult et al recovered the key from Hitag2 stream cipher in 360 seconds. The importance of the Hitag2 is primarily used in RFID transponder systems manufactured by Philips/NXP, and used by many car manufacturers for unlocking car doors remotely.

2.11.9 Guess and Determine Attack [46]

According with Ahmadi and Eghlidos the Guess and Determine Attack is defined as:

" In GD attacks, the attacker first guesses (the values of) a set of state elements of the cryptosystem, called a basis; hence, the name. The basis can correspond to different elements of different states (multiple times). Next, she determines the remaining state elements and running key sequence, and compares the resulting key sequence with the observed key sequence. If these two sequences are equal, then the guessed values are true and the cryptosystem has been broken, otherwise the attacker should repeat the above scenario with other guessed values". [47] Other application of this attack was proposed by Sha and Mahalanobis They used the GD attack on the A5/1 Stream cipher. Using the GD attack they recovered the key in a time complexity of 248:5, wich is much less than the bruteforce attack with a complexity of 264.

In the moment, Dunkelman and Keller made a cryptanalysis of the stream cipher LEX and in this cryptanalysis they used the GD attack. He started the GD attacks on LFSRs for stream ciphers.[48]



Chapter Three Particle Swarm Optimization

3.1 Introduction

The social behavior of animals, and in some cases of humans, is governed by similar rules. However, human social behavior is more complex than a flock's movement. Besides physical motion, humans adjust their beliefs, moving, thus, in a belief space. Although two persons cannot occupy the same space of their physical environment, they can have the same beliefs, occupying the same position in the belief space, without collision [38].

PSO was originally developed by a social-psychologist (James Kennedy) and an electrical engineer (Russell Eberhart) in 1995 and emerged from earlier experiments with algorithms that modeled the "flocking behavior" seen in many species of birds. Where birds are attracted to a roosting area in simulations they would begin by flying around with no particular destination and in spontaneously formed flocks until one of the birds flew over the roosting area [41].

PSO has been an increasingly hot topic in the area of computational intelligence. PSO is yet another optimization algorithm that falls under the soft computing umbrella that covers genetic and evolutionary computing algorithms as well. As such, it lends itself as being applicable to a wide variety of optimization problems.

3.2 Simulation Social Behavior [24]

A number of scientists have created computer simulations of various interpretations of the movement of organisms in a bird flock or fish school. Notably and et al presented simulations of bird flocking.

Reynolds was intrigued by the aesthetics of bird flocking choreography, and Heppner, a zoologist, was interested in discovering the underlying rules that enabled large numbers of birds to flock synchronously, often changing direction suddenly, scattering and regrouping, etc. Both of these scientists had the insight that local processes, such as those modeled by cellular automata, might underlie the unpredictable group dynamics of bird social behavior. Both models relied heavily on manipulation of inter-individual distances; that is, the synchrony of flocking behavior was thought to be a function of birds' efforts to maintain an optimum distance between themselves and their neighbors. It does not seem a too-large leap of logic to suppose that some same rules underlie animal social behavior, including herds, schools, and flocks, and that of humans. As sociobiologist "E. O. Wilson" has written, in reference to fish schooling, "In theory at least, individual members of the school can profit from the discoveries and previous experience of all other members of the school during the search for food. This advantage can become decisive, outweighing the disadvantages of competition for food items, whenever the resource is unpredictably distributed in patches".

3.3 Genetic Algorithms [34]

Genetic Algorithms are search algorithms based on the mechanics of natural selection and natural genetics. They combine survival of the fittest among string structures with a structured yet randomized information exchange to form a search algorithm with some of the innovative flair of human search. In every generation, a new set of artificial creatures (strings) is created using bits and pieces of the fittest of the old; an occasional new part is tried for good measure. While randomized, Genetic Algorithms are no simple random walk. They efficiently exploit historical information to speculate on new search point with expected improved performance.

GAs attempt to identify optimal solution by applying the techniques of natural selection to a population of solutions, the solutions are evaluated, the bad solutions are killed, and the remaining solutions are recombined (Mate) to form a new generation of solution.

The general principle is that of Darwinism the good traits will survive overtime as they are less likely to be on solutions that are killed a generation. Over a number generation in an overall increase in the quality of solution in the population.

Thus, a GA is an iterative procedure, which maintains a constant size population of candidate solution. During each iteration step (Generation) the structures in the current population are evaluated, and, on the basic of those evaluations, a new population of candidate solutions formed.

3.3.1 The Basic Cycle of GA

The basic GA cycle based on the three processes (selection, mating and mutation) as shown in figure (3.1) [51].



Figure (3.1) The Basic Cycle of GA

An abstract view of the GA is:

Generation=0;

Initialize G(P); {G=Generation ; P=Population}

Evaluate G(P);

While (GA has not converged or terminated)

Generation = Generation + 1; Select G(P) from G(P-1); Crossover G(P); Mutate G(P); Evaluate G(P);

End (While)

Terminate the GA. [54]

The GA main steps are as follows:

- 1. **The first step** is the selection process, which determines which string in the current generation will be used to create the next generation. By using move in the most promising direction in the overall search.
- 2. **The second step** is the mating process that determines the actual form of the string in the next generation [54]. At this point, two of the selected parents are paired. If the length of the each string is r, then a random number between 1 and r is selected, says, the mating process is one swapping bits s+1 to r of the first parent with bits s+1 to r of the second parent. In this way two new strings are created.
- 3. **The final step** is one of mutation. A fixed small mutation probability is set at the start of the algorithm. Bits in all the new string are then subject to change based on this mutation probability.

These three steps are repeated to create each new generation It continues in this fashion until some stopping condition is reached such as a maximum number of generation or a specified fitness value (threshold). [16]

The GA is usually stopped when a given termination condition is met. Some common termination conditions are:

- 1. A pre-determined number of generations have passed.
- 2. A satisfactory solution has been found.
- 3. No improvement in solution quality has taken place for a certain number of generations.

The different termination conditions are possible since a GA is not guaranteed to converge to a solution. [54]

3.4 Swarms and Particles [24]

It became obvious during the simplification of the paradigm that the behavior of the population of agents is now more like a swarm than a flock. The swarm has a basis in the literature. Millonas, developed his models for applications in "ALife", and articulated five basic principles of swarm intelligence, these principles are:

- 1. **Proximity principle**: the population should be able to carry out a simple space and time computations.
- 2. **Quality principle**: the population should be able to respond to quality factors in the environment.
- 3. **Principle of diverse response**: the population should not commit its activities along excessively narrow channels.
- 4. **Principle of stability**: the population should not change its mode of behavior every time the environment changes.
- 5. **Principle of adaptability**: the population must be able to change the behavior mode when it is worth the computational price.

Note that principles four and five above are the opposite sides of the same coin. The particle swarm optimization concept and paradigm presented in adhere to all five principles. Basic to the paradigm are ndimensional space calculations carried out over series of time steps.

The population members are mass-less and volume-less, and thus could be called "points," it is felt that velocities and accelerations are more appropriately applied to particles, even if each is defined to have arbitrarily small mass and volume. Further, Reeves discusses particle systems consisting of clouds of primitive particles as models of diffuse objects such as clouds, fire and smoke.

3.5 <u>Swarm Intelligence (SI)</u> [7]

In the last two decades, the computational researchers have been increasingly interested to the natural sciences, and especially biology, as sources of modeling paradigms.

Many research areas are massively influenced by the behavior of various biological entities and phenomena. It gave birth to most of population-based metaheuristics such as Evolutionary Algorithms (EAs), particle swarm optimization, and BA etc.

SI is a modern AI discipline that is concerned with the design of multi agent systems with applications, e.g. in optimization and robotics. The design paradigm for these systems is fundamentally different from many traditional approaches.

Instead of the sophisticated controller that governs the global behavior of the system, the SI principle is based on many unsophisticated entities that cooperate in order to exhibit a desired behavior. Inspiration for the design is taken from the collective behavior of social insects such as ants, termites, bees and wasps, as well as from the behavior of other animal societies such as flocks of birds or schools of fish. Colonies of social insects have mesmerized researchers for many years. However, the principles that govern their behavior remained unknown for a long time. Even though the single members of these societies are unsophisticated individuals, they are able to achieve complex tasks in cooperation.

Optimization techniques inspired by SI have become increasingly popular during the last decade. They are characterized by a decentralized way of working that mimics the behavior of swarms of social insects. The advantage of these approaches over traditional techniques is their robustness and flexibility.

These properties make SI a successful design paradigm for algorithm that deals with increasingly complex problems concerned with collective behavior in self-organized.

Bonabeau has defined the swarm intelligence as "any attempt to design algorithms or distributed problem-solving devices inspired by the collective behavior of social insect colonies and other animal societies"

3.5.1 Concepts of Swarm Intelligence [23]

Two fundamental concepts, self-organization and division of labor, are necessary and sufficient properties to obtain swarm intelligent behavior such as distributed problem solving systems that self-organize and adapt to the given environment these are:-

 Self-organization can be defined as a set of dynamical mechanisms, which result in structures at the global level of a system by means of interactions among its low-level components. These mechanisms establish basic rules for the interactions between the components of the system. The rules ensure that the interactions are executed on the basis of purely local information without any relation to the global pattern. Bonabeau et al. [6] have characterized four basic properties on which self-organization rely: Positive feedback, negative feedback, fluctuations and multiple interactions.

- **I)** Positive feedback is a simple behavioral "rules of thumb" that promotes the creation of convenient structures. Recruitment and reinforcement such as trail laying and following in some ant species or dances in bees can be shown as the examples of positive feedback.
- **II**) Negative feedback counterbalances positive feedback and helps to stabilize the collective pattern. In order to avoid the saturation which might occur in terms of available foragers, food source exhaustion, crowding or competition at the food sources, a negative feedback mechanism is needed.
- III) Fluctuations such as random walks, errors, random task switching among swarm individuals are vital for creativity and innovation. Randomness is often crucial for emergent structures since it enables the discovery of new solutions.
- **IV**) Self-Organization requires a minimal degree of mutuality to learned

individuals, enabling them to make use of the results from their own activities as well as others.

2. Inside a swarm, there are different tasks, which are performed simultaneously by specialized individuals. This kind of phenomenon is called division of labour. Simultaneous task performance by cooperating specialized individuals is believed to be more efficient than the sequential task performance by unspecialized individuals. Division of labour also enables the swarm to respond to changed conditions in the search space.

Two fundamental concepts for the collective performance of a swarm presented above, self-organization and division of labour are necessary and sufficient properties to obtain swarm intelligent behaviour such as distributed problem-solving systems that selforganize and adapt to the given environment.

3.5.2 Ant Colony Optimization [37]

ACO is a class of optimization algorithms modeled on the actions of an ant colony. ACO methods are useful in problems that need to find paths to goals.

Artificial 'ants'—simulation agents—locate optimal solutions by moving through a parameter space representing all possible solutions. Natural ants lay down pheromones directing each other to resources while exploring their environment. The simulated 'ants' similarly record their positions and the quality of their solutions, so that in later simulation iterations more ants locate better solutions.

3.5.3 Bee Algorithm Optimization [58]

The Bees Algorithm (BA) is a population-based search algorithm, first developed in 2005 by Pham DT etc. and Karaboga independently. The algorithm mimics the food foraging behavior of swarms of honey bees. In its basic version, the algorithm performs a kind of neighborhood search combined with random search and can be used for optimization problems.

3.5.4 Particle Swarm Optimization [37]

PSO is an optimization algorithm for dealing with problems in which a best solution can be represented as a point or surface in an n-dimensional space.

Hypotheses are plotted in this space and seeded with an initial velocity, as well as a communication channel between the particles.

Particles then move through the solution space, and are evaluated according to some fitness criterion after each time step.

Over the time, particles are accelerated towards those particles within their communication grouping which have better fitness values. The main advantage of such an approach over other global minimization strategies such as simulated annealing is that the large numbers of members that make up the particle swarm make the technique impressively resilient to the problem of local minima.

3.6 <u>PSO Topology</u> [24]

The common uses of PSOs are either global version or local version of PSO. In the global version of PSO, each particle flies through the search space with a velocity that is dynamically adjusted according to the particles of personal best performance achieved so far and the best performance achieved so far by all the particles. While in the local version of PSO, each particle's velocity is adjusted according to its personal best and the best performance achieved as far within its neighborhood. The neighborhood of each particle is generally defined as topologically nearest particle to the particle at each side.

Since then, a lot of researchers have worked on improving its performance by designing or implementing different types of neighborhood structures in PSOs. Each neighborhood structure has its strength and weakness. It works better in one kind of problems, but worse on the other kind of problems. When using PSO to solve a problem, not only the problem needs to be specified, but the neighborhood structure of the PSO utilized, should also be clearly specified.

3.7 <u>PSO Algorithm</u> [24]

The PSO algorithm depends in its implementation in the following two relations:

 $v_{id} = w * v_{id} + c_1 * r_1 * (p_{id} - x_{id}) + c_2 * r_2 * (p_{gd} - x_{id})$...(3.1a) $x_{id} = x_{id} + v_{id}$...(3.1b)

where c_1 and c_2 are positive constants, and r_1 and r_2 are random function in the range [0,1], $x_i = (x_{i1}, x_{i2}, ..., x_{id})$ represents the ith particle; $p_i = (p_{i1}, p_{i2}, ..., p_{id})$ represents the best previous position (the position giving the best fitness value) of the ith particle; the symbol *g* represents the index of the best particle among all the particles in the population, $v = (v_{i1}, v_{i2}, ..., v_{id})$ represents the rate of the position change (velocity) for particle *i*.

Equation (3.1) is the equation describing the flying trajectory of a population of particles. Equation (3.1a) describes how the velocity is dynamically updated and Equation (3.1b) the position update of the changed abruptly. It is changed from the "flying" particles. Equation (3.1a) consists of three parts. The first part is the momentum part. The velocity can't be current velocity. The second part is the "cognitive" part which represents private thinking of itself - learning from its own flying experience. The third part is the "social" part that represents the collaboration among particles learning from group flying experience.

In equation (3.1a), if the sum of the three parts on the right side exceeds a constant value specified by user, then the velocity on that dimension is assigned to be $\pm v_{max}$, that is, particle's velocities on each dimension is clamped, to a maximum velocity v_{max} , which is an important parameter, and originally is the only parameter required to be adjusted by

users. Big v_{max} has particles that have the potential to fly far past good solution areas while a small v_{max} has particles that have the potential to be trapped into local minima, therefore they are unable to fly into better solution areas. Usually a fixed constant value is used as the v_{max} , but a well-designed dynamically changing v_{max} might improve the PSO's performance.

The PSO algorithm is simple in concept, easy to implement and computational efficient. The original procedure for implementing PSO is as follows:

- Initialize a population of particles with random positions and velocities on d-dimensions in the problem space.
- 2. PSO operation includes:
 - a. For each particle, evaluate the desired optimization fitness function in

d variables.

- b. Compare particle's fitness evaluation with its pbest. If current value is better than pbest, then set pbest equal to the current value, and p_i equals to the current location x_i in d-dimensional space.
- c. Identify the particle in the neighborhood with the best success so far, and assign its index to the variable g.
- d. Change the velocity and position of the particle according to equation (3.1a) and (3.1b).
- 3. Loop to step (2) until a criterion is met, usually a sufficiently good fitness or a maximum number of iterations.

Like the other evolutionary algorithms, a PSO algorithm is a population based on search algorithm with random initialization, and there is an interaction among population members. Unlike the other evolutionary algorithms, in PSO, each particle flies through the solution space, and has the ability to remember its previous best position, survives from generation to generation. Furthermore, compared with the other evolutionary algorithms,
e.g. evolutionary programming, the original version of PSO is faster in initial convergence through simplified social model while it is lower in fine tuning. The flow chart of PSO algorithm is shown in figure (3.2). [59]



Figure (3.2) Flowchart of PSO Algorithm [58].

3.8 The Parameters of PSO

A number of factors will affect the performance of the PSO. These factors are called PSO parameters, these parameters are:

- Number of particles in the swarm affects the run-time significantly, thus a balance between variety (more particles) and speed (less particles) must be sought.
- 2. Maximum velocity (v_{max}) parameter. This parameter limits the maximum jump that a particle can make in one step, thus a too large value for this parameter will result in oscillations, while a too small value could cause the particle to become trapped in a local minima. The maximum velocity parameter is set to the default value of 2 (this value was suggested in earlier works in PSO). [48]
- 3. The role of the inertia weight *w*, in equation (3.2a), is considered critical for the PSO's convergence behavior. The inertia weight is employed to control the impact of the previous history of velocities on the current one. A large inertia weight facilitates global exploration (searching new areas); while a small one tends to facilitate local exploration, i.e., fine-tuning the current search area. Experimental results indicate that it is better to initially set the inertia to a large value, in order to promote global exploration of the search space, and gradually decrease it to get more refined solutions. Thus, an initial value around 1.2 and a gradual decline towards 0 can be considered as a good choice for *w*. [41]
- 4. The parameters c_1 and c_2 in equation (3.1a), are not critical for PSO's Convergence. However, proper fine-tuning may result in faster convergence and alleviation of local minima. An extended study of the acceleration parameter in the first version of PSO is given in

recent work reports that it might be even better to choose a larger cognitive parameter, c_1 than a social parameter c_2 but with $c_1 + c_2 = 4$.

5. The parameters r_1 and r_2 are used to maintain the diversity of the population, and they are uniformly distributed in the range [0,1]. [41]

From the above case, we can learn that there are two key steps when applying PSO to optimization problems: the representation of the solution and the fitness function. One of the advantages of PSO is that PSO takes real numbers as particles.

Secondly global version vs. local version: We have introduced two versions of PSO; global and local versions. Global version is faster but might converge to local optimum for some problems. Local version is a little bit slower but not easy to be trapped into local optimum. One may use global version to get quick results and use local version to refine the search [20]. The most common parameters of PSO are shown in table (3.1).

No.	Parameter	Symbol	Parameter value
1	No. of particles	Psize	$P_{size \in [10-40]}$
2	Maximum velocity	$v_{\rm max}$	$v_{\rm max} = 2$
	Minimum velocity	$v_{\rm min}$	$v_{\rm min} = - v_{\rm max}$
3	Inertia weight	w	$w \in [0.4, 0.9]$
4	First acceleration parameter	<i>C</i> ₁	$c_1 \in [0.5, 2]$
	Second acceleration parameter	<i>C</i> ₂	$c_1 = c_2$ or $c_{1+} c_2 = 4$
5	Diversity of the population	r_1, r_2	$r_1, r_2 \in [0,1]$
6	Iterations	Iter.	≤ 30000

Table (3.1) the most common Parameters of PSO.



Chapter four

PSO Cryptanalysis Stream Cipher Cryptosystems

4.1 Introduction

In stream cipher systems field, the Linear Feedback Shift Register (LFSR) cryptosystems used widely. In this chapter, first, a method introduced to construct a linear equations system of a single LFSR. This method developed to construct a system of linear equations (SLE) of the attacked a LFSR cryptosystem, where the effect of combining function CF) of LFSR is considerable. Three study cases are suggested to be cryptanalyzed: Single LFSR, Linear, and Threshold.

This thesis aims to find the initial values of every LFSR in the attacked cryptosystem, using proposed PSO cryptanalysis system, depending on the following information:

- 1. The length of every LFSR and its feedback polynomial are known.
- 2. The algebraic description of CF is known.
- 3. The keystream (output sequence S) generated from the LFSRS is known, or part of it, practically, that means, a known plain attack be applied [47].

This research consists of three stages, constructing the SLE, applying the proposed PSO cryptanalysis system to solve SLE and find the actual initial key for the attacked cryptosystem, and lastly, decrypt the ciphertext to obtain the real plaintext.

4.2 <u>Constructing SLE for Stream Cipher Cryptosystems</u>

LFSRs are used widely in stream cipher systems field. A LFSR System consists of two main basic units. First, a LFSR function and initial state values. The second one is, the *Combining Function* (CF), which is represented by a Boolean function. Most of all stream cipher systems depend on these two basic units. This section, describes the attack of three case studies of stream ciphers using PSO algorithm.

4.2.1 Single LFSR Stream Cipher Cryptosystem (SLSCC)

The first case study which we want to attack, is a single LFSR, which this system has no combining function, so we expect that it's can be expressed as one linear equations system.

Most practical stream cipher cryptosystems designs center around LFSR. In the early days of electronics machines, they were easy to build. A SR is an array of bit memories and the feedback sequence is only a series of XOR gates. A LFSR-based on stream cipher gives a lot of security with only a few logic gates.

To see how the SLSCC acts, let's assume, a 4-bit LFSR has $1+x+x^4$ recursive polynomial. If it is initialized with the value 1010, it produces the following sequence of internal states before repeating; See Table (4.1):

1	0	1	0
1	1	0	1
0	1	1	0
0	0	1	1
1	0	0	1
0	1	0	0
0	0	1	0

Table (4.1): SLSCC with length L=4.

The output sequence is the string of least significant bits: 0101100.

Let SR_L be a single LFSR with length L, let $A_0=(a_{-1},a_{-2},...,a_{-L})$ be the initial value key vector of SR_L , s.t. a_{-j} , $1 \le j \le L$, be the component j of the vector A_0 , this mean, a_{-j} is the initial bit of stage j of SR_L . Let $C_0^{T}=(c_1,...,c_L)$ be the feedback vector, where $c_j \in \{0,1\}$, if $c_j=1$ this means that the stage j is connected else it's not connected. Let $S=\{s_i\}_{i=0}^{m-1}$ or $S=(s_0,s_1,...,s_{m-1})$ be the sequence with length m generated from SR_L . The generation of S depending on the following relation:

$$s_i = a_i = \sum_{j=1}^{L} a_{i-j} c_j$$
 i=0,1,... ...(4.1)

Relation (4.1) represents the linear recurrence relation [4]. The objective is finding the vector A_0 , when L, C_0 and S are all known. Let M be a L×L matrix, which is describes the initial phase of SR_L: $M=(C_0|I_{L\times L-1})$, where $M^0=I$.

Let A₁ represents the new initial of SR_L after one shift, s.t.

$$A_{1}=A_{0}\times M=(a_{-1},a_{-2},\ldots,a_{-L})\begin{pmatrix}c_{1} & 1 & \cdots & 0\\c_{2} & 0 & \cdots & 0\\\vdots & \vdots & \vdots & \vdots\\c_{L} & 0 & \cdots & 0\end{pmatrix}=(\sum_{j=1}^{L}a_{-j}c_{j},a_{-1},\ldots,a_{1-L}).$$

In general,

$$A_i = A_{i-1} \times M, i = 0, 1, 2, ...$$
 ...(4.2)

Equation (4.2) can be considered as a recurrence relation, so we have:

$$A_i = A_{i-1} \times M = A_{i-2} \times M^2 = \dots = A_0 \times M^1$$
 ...(4.3)

notice that:

 $M^2 = [C_1C_0|I_{L\times L-2}]$ and so on until get $M^i = [C_{i-1}...C_0|I_{L\times L-i}]$, where $1 \le i < L$. When $C_P = C_0$ then $M^{P+1} = M$, where P is the period of the vector C. Now we can calculate C_i [¹] as follows:

$$C_i = M \times C_{i-1}, i = 1, 2, \dots$$
 ...(4.4)

Relation (4.3) can be rewritten in matrix form:

$$A_0 \times C_i = s_i, i = 0, 1, ..., L-1$$
(4.5)

if i=0 then $A_0 \times C_0 = s_0$ is the 1st equation of the SLE, if i=1 then $A_0 \times C_1 = s_1$ is the 2nd equation of the SLE, and if i=L-1 then $A_0 \times C_{L-1} = s_{L-1}$ is the Lth equation of the SLE. In general:

$$A_0 \times \Omega = S$$
 ...(4.6)

 Ω represents the matrix of all C_i vectors s.t.

$$\Omega = (C_0 C_1 \dots C_{L-1}) \dots (4.7)$$

The SLE can be formulated as follows:

$$\Lambda = [\Omega^{\mathrm{T}} | \mathrm{S}^{\mathrm{T}}] \qquad \dots (4.8)$$

 Λ represents the extended (augmented) matrix of the SLE.

Example (4.1)

Let the SR₃ has $C_0^T = (0,1,1)$ and S=(0,0,1), by using equation (4.6), we get:

$$C_{1}=M\times C_{0}=\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}\begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}=\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \text{ in the same way, } C_{2}=\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

From equation (4.8) we have:

$$A_{0} \begin{pmatrix} 0 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} = (0,0,1), \text{ this system can be written as equations:}$$

$$a_{-2}+a_{-3}=0$$

$$a_{-1}+a_{-2} = 0$$

$$a_{-1}+a_{-2}+a_{-3}=1$$

Then the augmented matrix Λ of SLE after using formula (4.8) is:

	0	1	1	0	
$\Lambda =$	1	1	0	0	(4.9)
	1	1	1	1	

The pseudo code of constructing the SLE (find the extended matrix Λ) for single LFSR algorithm is:

NAME : Constructing SLE for SLSCC Algorithm (CSLESRA).

: L, C₀, S {*length of LFSR, feedback vector, output seq.*} INPUT : Construct the Matrix M { $M = [C_0/I_{L\times L-1}]$ } PROCESS Construct the Matrix $\Omega = (C_0C_1...C_{L-1})$: The SLE $\Lambda = [\Omega^T | S^T]$ {*the extended matrix of LES* } OUTPUT

4.2.2 Linear Stream Cipher Cryptosystem (LSCC)

The second case study that is applied in this thesis in the cryptanalysis of stream cipher is the linear function or XOR gate. Figure (4.1) describes the sequence S generated from the linear system.





The output of each LFSR in the system is known as the simplest balance system. It is expected that each LFSR can be expressed by one SLE, but, each has unknown absolute values, since the output of each LFSR is unknown. Then, we concatenate the constructed **LSCC** with each other to construct one SLE with known absolute values. For example, the logical truth table of the combining function of 2-LFSR's linear cryptosystem is as shown in Table (4.2).

Table (4.2): The XOR relation for LSCC, n=2.

		X ₁	
		0	1
	0	0	1
X ₂	1	1	0

Let's have n of SR_{L_j} with length L_j , j=1,2,...,n, with following feedback vector:

$$C_{0j} = \begin{pmatrix} c_{01j} \\ c_{02j} \\ \vdots \\ c_{0r_jj} \end{pmatrix}, \text{ and has unknown initial value vector } A_{0j} = (a_{-1j}, \dots, a_{-Lj}), \text{ so}$$

 $SR_{L_j} has M_j = (C_{0j}|I_{L_j \times L_j - 1})$

By using recurrence equation (4.4),

$$C_{ij} = M_j \times C_{i-1,j}, i=1,2,...$$
 ...(4.10)

by using equation (4.5):

 $A_{0j} \times C_{ij} = s_{ij}, i=0,1,...,L-1 \text{ and } S_j = (s_{0j},s_{1j},...,s_{m-1,j}).$

 S_j represents the output vector of SR_{L_j} , which of course, is unknown too. m represents the number of variables produced from the LFSR's with consider to CF, in the same time its represents the number of equations which are be needed to solve the SLE. Of course, there is n of SLE (one SLE for each SR_{L_i} with unknown absolute values).

Now, let A_0 be the extended vector for m variables, which consists of initial values from all LFSR's and Ω is the matrix of C_i vectors considering the CF, C_i represents the extended vector of all feedback vectors C_{ij} , then $A_0 \times \Omega = S$.

As known, the outputs of every LFSR of the LSCC are XORed with each other to obtain the sequence S which is generating from this cryptosystem. Since the SR_{L_j} has L_j number of unknown initial values, then $m = \sum_{j=1}^{n} L_j$.

Now, all the vectors A_{0j} are extended from r_j to m as follows:

$$A_{01} = (a_{11}, \dots, a_{L_1}, 0, \dots, 0, \dots, 0)$$

$$A_{02}=(0...0,a_{12},...,a_{L,2},...,0...0)$$

And so on..

$$A_{0n} = (0 \dots 0, 0 \dots 0, \dots, a_{1n}, \dots, a_{L_n})$$

And let:

$$A_0 = \sum_{j=1}^{n} A_{0j} = (a_{11}, \dots, a_{L_1 1}, a_{12}, \dots, a_{L_2 2}, \dots, a_{1n}, \dots, a_{L_n n}) = (l_0, l_1, \dots, l_{m-1})$$

Where $l_0=a_{11}$, $l_1=a_{21}$,..., $l_{m-1}=a_{L_nn}$, or it can be deduced from the following formula:

$$l_k = a_{ij}$$
, where $k = (i-1) + \sum_{h=1}^{j-1} L_h$, $j = 1, 2, ..., n, i = 1, 2, ..., L_j$(4.11)

In fact, A_0 represents a concatenation of all A_{0j} vectors respectively. The same process will be done on the feedback vectors C_{ij} which must be found first from equation (4.10). Therefore, C_i will be the extended concatenation vector of all feedback C_{ij} vectors too, s.t.

$$C_{i} = \begin{pmatrix} C_{i1} \\ C_{i2} \\ \vdots \\ C_{in} \end{pmatrix}, i = 0, 1, \dots, m-1$$

Since the CF of LSCC is XOR, then S can be obtained from XORed all unknowns S_j . Since we need m equations, that means every LFSR shifts m movements, then:

$$S_j = (s_{0j}, s_{1j}, \dots, s_{m-1,j}), j = 1, 2, \dots, n, and s_i = \sum_{j=1}^n s_{ij}, i = 0, 1, \dots, m-1, (the sum)$$

here is XOR), then:

$$S = \sum_{j=1}^{n} S_{j} = (s_{0}, s_{1}, \dots, s_{m-1})$$

So Ω can be gotten from equation (4.7) and by applying equation (4.6), the SLE can be constructed.

The pseudo code of constructing the SLE for linear system algorithm is:



Example (4.2)

Let's have the following feedback vectors for 3 LFSR with length 2,3 and 4:

$$C_{01} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, C_{02} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \text{ and } C_{03} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \text{ then m=9.}$$

And let S=(1,1,1,0,1,1,0,1,1).

By using equation (4.4),

$$C_{01}=C_{31}=C_{61}=\begin{pmatrix}1\\1\end{pmatrix}, C_{11}=C_{41}=C_{71}=\begin{pmatrix}0\\1\end{pmatrix}, \text{ and } C_{21}=C_{51}=C_{81}=\begin{pmatrix}1\\0\end{pmatrix}$$

Then $C_0^T = (1,1,1,0,1,1,0,0,1).$

The SLE can be written as follows:

$$A_0 \begin{pmatrix} 1 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 1 & 1 & 0 & 1 & 1 & 0 \\ 1 & 1 & 0 & 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 0 & 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 & 1 & 0 & 0 & 1 & 1 \\ 1 & 1 & 1 & 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 1 & 0 & 1 & 0 & 1 \\ 1 & 1 & 1 & 1 & 0 & 1 & 0 & 1 & 1 \end{pmatrix} = (1,1,1,0,1,1,0,1,1)$$

s.t.

 $A_0 = (a_{11}, a_{21}, a_{12}, a_{22}, a_{32}, a_{13}, a_{23}, a_{33}, a_{43}) = (l_0, l_1, l_2, l_3, l_4, l_5, l_6, l_7, l_8)$, and the extended matrix Λ which is can be calculated from equation (4.8) is:

	1	1	1	0	1	1	0	0	1	1]
	0	1	1	1	1	1	0	1	1	1
	1	0	0	1	1	1	1	1	1	1
	1	1	1	1	0	0	1	1	1	0
Λ=	0	1	0	0	1	1	1	1	0	1
	1	0	0	1	0	0	1	0	1	1
	1	1	1	0	0	1	0	1	0	0
	0	1	1	0	1	1	1	0	1	1
	1	0	1	1	1	0	0	1	1	1

...(4.12)

4.2.3 Nonlinear Threshold Stream Cipher Cryptosystem (NTSCC)

The third proposed study case, is the Threshold Generator known. Its CF called the majority function. This cryptosystem consists of odd numbers of LFSRs, so naturally, there are a majority in the output bits of one or another, this means, which one is the major, will be the output. So it can be represented by following equation:

 $BF_3(x_1,x_2,x_3)=x_1.x_2 \oplus x_1.x_3 \oplus x_2.x_3$

Table (4.3) shows the truth table of 3-LFSR's of Threshold generator cryptosystem.

X ₁	X ₂	X ₃	BF ₃
0	0	0	0
0	0	1	0
0	1	0	0
0	1	1	1

Table (4.3): The 3-LFSR's of NTSCC Generator.

1	0	0	0
1	0	1	1
1	1	0	1
1	1	1	1

for this reason $m=L_1L_2+L_1L_3+L_2L_3$.

The initial value of this cryptosystem is:

 $A_0 = A_{01}A_{02} + A_{01}A_{03} + A_{02}A_{03} = (d_0, d_1, \dots, d_{m-1}) \qquad \dots (4.13)$

(where + is concatenation to the vectors) s.t.

 $d_0=a_{-11}a_{-12}$, $d_1=a_{-11}a_{-22}$,..., $d_{r-1}=a_{L_22}a_{L_33}$, or it can be taken from the following System of NonLinear Equations (SNLE):

$$d_{k} = \begin{cases} a_{-i1}a_{-j2}, \text{ when } k = i * L_{2} + j, \text{ s.t. } i = 0, \dots, L_{1} - 1, \quad j = 0, \dots, L_{2} - 1 \\ a_{-i1}a_{-j3}, \text{ when } k = i * L_{3} + j + L_{1}L_{2}, \text{ s.t. } i = 0, \dots, L_{1} - 1, \quad j = 0, \dots, L_{3} - 1 \\ a_{-i2}a_{-j3}, \text{ when } k = i * L_{3} + j + L_{1}L_{2} + L_{1}L_{3}, \text{ s.t. } i = 0, \dots, L_{2} - 1, \quad j = 0, \dots, L_{3} - 1 \end{cases}$$

$$(4.14)$$

(this arrangement of unknowns can be changed according to the researcher requirements so it is not standard).

In the same way, equation (4.14) can be applied on the feedback vector C_{ij} :

 $C_i = C_{i1}C_{i2} + C_{i1}C_{i3} + C_{i2}C_{i3}.$

And the sequence S will be:

 $S=S_1S_2+S_1S_3+S_2S_3 \text{ s.t. } s_i=s_{i1}s_{i2} \oplus s_{i1}s_{i3} \oplus s_{i2}s_{i3},$

s_i is the element i of S.

So the SNLE which be changed to SLE can be gotten by equation (4.13).

Figure (4.2) shows the sequence S which is generated from Brüer Generator [ξ].



The pseudo code of constructing the SLE for NTSCC algorithm is:

NAME : Constructing SLE for NTSCC Algorithm (CSLENTSA). : S **INPUT** $L_i, C_{0i}, j = 1:3$: Calculate $m = L_1 * L_2 + L_1 * L_3 + L_2 * L_3$ **PROCESS** for j = 1 : 3Construct the Matrix M_i **end**; {*for j* } $C_{0j} = C_{01j} * C_{02j} + C_{01j} * C_{03j} + C_{02j} * C_{03j}$ **for** i = 0 : m-1 $C_{ij} = C_{i1j} * C_{i2j} + C_{i1j} * C_{i3j} + C_{i2j} * C_{i3j}$ **end**; {*for i* } **for** i = 0 : m-1 $C_i = C_{i1} * C_{i2} + C_{i1} * C_{i3} + C_{i2} * C_{i3}$ **end**; {*for i* } Construct the Matrix $\Omega = (C_0C_1...C_{m-1})$: The SLE $\Lambda = [\Omega^{T} | S^{T}] \{ the extended matrix of SLE \}$ **OUTPUT** END.

Example (4.3)

Let's have the following feedback vectors for 3 LFSR with length 2,3 and 4:

by applying equation (4.4), C_0^{T} will be:

 $C_0^{T} = (1,0,1,1,0,1,1,0,0,1,1,0,0,1,1,0,0,1,0,0,0,0,1,0,0,1).$ Therefore the augmented matrix will be:

4.3 The Proposed PSO Cryptanalysis System (PSOCS)

PSO is an extremely simple concept, and can be implemented without complex data structure. No complex or costly mathematical functions are used, and it doesn't require a great amount of memory [49]. The facts of PSO has fast convergence, only a small number of control parameters, very simple computations, good performance, and the lack of derivative computations made it an attractive option for solving the problems.

In this thesis we will use one of important methods of swarm intelligence methods; it's the PSO method, in the field of cryptanalysis of stream cipher systems, which it has good achievement in the cryptanalysis field. Before we discuss the operators and parameters of PSOCS we will show how the system constructs the SLE.

4.3.1 <u>PSOCS Constructing a SLE</u>

Before we start the attack of a certain class of stream ciphers using PSOSC, the first step is to select the known algorithm that will be attacked. The second step is to prepare the constructed key equations for m steps, where m is the length of string. These equations will be represented in binary form.

I. PSOCS Constructing a SLE for SLSCC

For example, let us use 10-stage m-LFSR, which has $1+x^3+x^{10}$ as characteristic primitive polynomial. Table (4.4) shows the 10-stage

equations of LES for single LFSR with binary representation.

Eq. No.	Equation	Binary Code
1	a ₃ +a ₁₀ =1	0010000001 1
2	$a_2 + a_9 = 0$	010000010 0
3	$a_1 + a_8 = 1$	100000100 1
4	$a_3 + a_7 + a_{10} = 1$	0010001001 1
5	$a_2 + a_6 + a_9 = 0$	0100010010 0
6	$a_1 + a_5 + a_8 = 1$	1000100100 1
7	$a_3 + a_4 + a_7 + a_{10} = 1$	0011001001 1
8	$a_2 + a_3 + a_6 + a_9 = 0$	0110010010 0
9	$a_1 + a_2 + a_5 + a_8 = 1$	1100100100 1
10	$a_1 + a_3 + a_4 + a_7 + a_{10} = 0$	1011001001 0

Table (4.4) SLE for SRSCC with binary representation.

II. PSOCS Constructing a SLE for SLSCC

For example, let us use two LFSR's. Each has the following

information:

- First LFSR has characteristic polynomial 1+x+x⁴ with initial key values 1001.
- Second LFSR has characteristic polynomial 1+x+x⁷ with initial key values 1000001.

The equations of SLE for the linear cryptosystem are shown in Table (4.5).

Eq. No.	Separating Equations	Single Equations	Binary Code
1	$a_1 + a_4 = 0b_1 + b_7 = 0$	$a_1 + a_4 + b_1 + b_7 = 0$	10011000001 0
2	$a_1 + a_3 + a_4 = 0b_1 + b_6 + b_7 = 0$	$a_1 + a_3 + a_4 + b_1 + b_6 + b_7 = 0$	10111000011 0
3	$a_1 + a_2 + a_3 + a_4 = 0 \dots b_1 + b_5 + b_6 + b_7 = 0$	$a_1+a_2+a_3+a_4+b_1+b_5+b_6+b_7=0$	11111000111 0
4	$a_2+a_3+a_4=1b_1+b_4+b_5+b_6+b_7=0$	$a_2+a_3+a_4+b_1+b_4+b_5+b_6+b_7=1$	01111001111 1
5	$a_1+a_2+a_3=1b_1+b_3+b_4+b_5+b_6+b_7=0$	$a_1+a_2+a_3+b_1+b_3+b_4+b_5+b_6+b_7=1$	11101011111 1
6	$a_2+a_4=1b_1+b_2+b_3+b_4+b_5+b_6+b_7=0$	$a_2+a_4+b_1+b_2+b_3+b_4+b_5+b_6+b_7=1$	0101111111111
7	$a_1 + a_3 = 1 \dots b_2 + b_3 + b_4 + b_5 + b_6 + b_7 = 1$	$a_1+a_3+b_2+b_3+b_4+b_5+b_6+b_7=0$	10100111111 0
8	$a_1+a_2+a_4=0b_1+b_2+b_3+b_4+b_5+b_6=1$	$a_1+a_2+a_4+b_1+b_2+b_3+b_4+b_5+b_6=1$	11011111110 1
9	$a_3+a_4=1b_2+b_3+b_4+b_5+b_7=1$	$a_3+a_4+b_2+b_3+b_4+b_5+b_7=0$	00110111101 0
10	$a_2+a_3=0b_1+b_2+b_3+b_4+b_6=1$	$a_2+a_3+b_1+b_2+b_3+b_4+b_6=1$	01101111010 1
11	$a_1+a_2=1b_2+b_3+b_5+b_7=1$	$a_1+a_2+b_2+b_3+b_5+b_7=0$	11000110101 0

Table (4.5) SLE for SLSCC with binary representation.

III. PSOCS Constructing a SLE for STSCC

Three LFSR's are used, each has the following information:

 \Box 1st LFSR has characteristic polynomial 1+x+x³ with initial key values

101.

- \Box 2nd LFSR has characteristic polynomial 1+x+x⁴ with initial key values 1001.
- \Box 3rd LFSR has characteristic polynomial 1+x²+x⁵ with initial key values 10001.

When the SNLE changes, 47 equations of SLE are obtained for the

Threshold generator cryptosystem shown in Table (4.6).

Eq. No.	Equations	Binary Code	Extension of Equations in Binary Code
1	$a_1+a_3=0b_1+b_4=0c_2+c_5=1$	101100101001 0	10010000100101001000000100101000000000
2	$a_1+a_2+a_3=0b_1+b_3+b_4=0c_1+c_4=1$	111101110010 0	101110111011100101001010010100000001001
3	$a_2+a_3=1b_1+b_2+b_3+b_4=0c_2+c_3+c_5=1$	011111101101 1	0000111111110000001101011010110101101011010
4	$a_1+a_2=1b_2+b_3+b_4=1c_1+c_2+c_4=1$	110011111010 1	01110111000011010110100000000001101011010
5	$a_3=1b_1+b_2+b_3=1c_1+c_2+c_3+c_5=0$	001111011101 1	000000001110000000000111011110111101111010

Table (4.6) SLE for STSCC with binary representation.

41	$a_2=0b_1+b_2=1c_4+c_5=1$	010110000011	0000110000000000001100000001100011000000
42	$a_1 = 1b_4 = 1c_3 + c_4 = 0$	100000100110 1	00010000000001100000000000000000000000
43	$a_1+a_3=0b_3=0c_2+c_3=0$	101001001100 0	00100000010011000000011000000000000110000
44	$a_1+a_2+a_3=0b_2=0c_1+c_2=1$	111010011000 0	0100010001001100011000110000000011000000
45	$a_2+a_3=1b_1=1c_1+c_2+c_5=0$	011100011001 1	10001010010010010000000000000000000000
46	$a_1+a_2=1b_1+b_4=0c_1+c_2+c_4+c_5=0$	110100111011 0	0010001000100100001100011000100001100000
47	$a_3=1b_1+b_3+b_4=0c_1+c_2+c_3+c_4+c_5=0$	001101111111 0	01000100010011000110001100010000011000010000

Each time, m equations are needed to solve the system for each cryptosystem. First, one is the SLE of SRSCC, where m here equals the length of LFSR. The second, is the SLE of SLSCC, m represents the summation of the two combined LFSR's. While the third, is the SNLE of STSCC, which needs

m = $r_1*r_2+r_1*r_3+r_2*r_3$, where r_i is length of register i, i=1,2,3, to solve the system.

4.3.2 <u>Representation of a Random Solution</u>

For the purpose of this study, a SLE or SNLE is decoded by a binary code. For example the equation $a_2 \bigoplus a_2=1$ of a single LFSR with length 5 is decoded by the equation string (01001-1), where the absolute value (right hand) of the equation is the real output key of the attacked cryptosystem. The equations must be constructed and stored in data base file, since these equations are constant for fixed LFSR's length according to the connection function and combining function (if it exist). This representation indicates that the size of the solutions space is 2^{m} -1 (ignoring the zero string). When m is as large as possible, then a purely random search is not acceptable.

4.3.3 Swarm Solution Initialization

For the initialization process, it can initialize the population of the swarm by a random sample of combinations of 0 and 1 with *m*-string length which represents the probable initial values LFSR's. The creation of the swarm's population must submit to what we called non-zero initial condition. In this condition, the zero's initial of LFSR's must be avoided. For example, you wish to initiate initial values of LFSR with length 5; you ignore the initial value 00000 for single LFSR or other cryptosystems. Another example the string 00001100100 is ignored for linear cryptosystem, which consists of two LFSR's with lengths 4 and 7 respectively, since the initial of the first register, is 0000. A pseudo code for generating the swarm initialization is shown below:

NAME : Swarm Initialization Algorithm (SIA).{Swarm Size, Length of Particle}: SS, LINPUT: for i = 1 : SSPROCESSfor j = 1 : L $p_j = Random(2);$ $v_j = Random(2);$ end;Particle_P(i)=(s_1,s_2,...,s_L); {position}Particle_V(i)=(v_1,v_2,...,v_L); {velocity}{ position and velocity }: Swarm of ParticlesOUTPUT

4.3.4 PSOSC Fitness Function

The fitness function is used to determine the "best" solution. The process of the fitness function selection is as follows:

- From swarm, a particle initial solution of length n-bits is extended to *m* bits; m=L₁⊕L₂⊕L₃ for linear system, m=L₁*L₂⊕L₁*L₃⊕L₂*L₃ for Threshold cryptosystem and it is remains as it is for the Single LFSR (m=n=L), so we get the vector A=(a₁,a₂,...,a_m) after extension.
- The extended string bit a_j product with corresponding equation vector bit x_j, where 1≤j≤m s.t. the equation string is X=(x₁,x₂,...,x_m) and calculate the observed value:

$$o_i = a_1 * x_1 \oplus a_2 * x_2 \oplus \ldots \oplus a_m * x_m = \sum_{j=1}^m a_j * x_j = AX^T$$
 ...(4.16)

Compare the observed value o_i with key value b_i which represents the known output value of the cryptosystem, by using mean absolute error (MAE), in general O=(o₁,o₂,...,o_m) and B=(b₁,b₂,...,b_m) s.t.

MAE =
$$\frac{1}{m} \sum_{i=1}^{m} |o_i - b_i| = \frac{1}{m} |O - B|$$
 ...(4.17)

4. The Fitness value is

Fitness = 1-MAE =
$$1 - \frac{1}{m} \sum_{i=1}^{m} |O_i - K_i|$$
 ...(4.18)

where

m : The length of the individual string or equation string.

a_j: is the initial value j in vector A.

 x_j : is the equation variable j in the string X.

 o_i : is the measured or observed value i in the vector O calculated from equation (4.16).

b_i: is the key bit (actual value) I in the vector B.

When the observed vector O matches the key vector B, for all $1 \le i \le m$, then the summation terms MAE in equation (4.17) evaluate to 0 so the fitness value is 1. The fitness equation is bounded below by 0 though it does not actually evaluate to 0. The fact that a fitness value of 0 is never achieved does not affect the algorithm since high fitness values are more important than low fitness values. As a result, the search process is always moving towards fitness values closer to or equal 1. The steps of the *Stream Cipher Fitness Algorithm* are shown below:

NAME : Stream Cipher Fitness Algorithm (SCFA). INPUT : READ A vector; {Initial string with length L} READ X vector; {Equation string from data base file} READ B vector ;{Actual key=absolute value of SLE} OUTPUT : Fitness value; PROCESS : FOR i = 1 : m $o_i = \sum_{j=1}^{m} a_j * x_j$; {XOR sum, O is observed key vector} $AE_i = |o_i - b_i|$; END; $MAE = \frac{1}{m} \sum_{i=1}^{m} AE_i$; {MAE is the Mean Absolute Error} Fitness = 1-MAE; END.

4.3.5 PSOSC Parameters Selection

As the main objective of this research is to verify the impact of the selection of social topologies in the behavior of the PSO, the tuning parameters are fixed. They are tuned to the values that are widely used by the community and that are seemed to be the most appropriate ones. Table (4.7) shows the different parameters used.

Table 4.7: Parameters selection of PSOCS

Parameter Symbol	Description	Value
<i>C</i> ₁	Self confidence	1.5 - 2.0

<i>c</i> ₂	Swarm Confidence	<i>c</i> ₁
W	Inertia weight	0.9,,0.4
<i>v</i> _{max}	maximum of velocity	0.5
v _{min}	minimum of velocity	-v _{max}
Swarm_Size	Number of particles in the swarm	30-50
Max_Iter	Maximum number of iteration	100-2000

4.3.6 The PSOCS Algorithm

The following are the main steps of an algorithmic description of the attack on stream cipher using PSOCS:

NAME : PSOCS algorithm (PSOCSA).

INPUT : The construction SLE/SNLE, parameters (c_1 , w, v_{max} , SS,

m,Max_Iter).

OUTPUT : The key having the highest fitness as found by PSOCS; **PROCESS** :

Step 1: Randomly generate the initial particles (keys) and velocities to a swarm. **Step 2**: Calculate the fitness value of each of the particles (keys) using equation (4.18).

Step 3: If the current position of the particle is better than the previous history, update the particles to indicate this fact.

Step 4: Find the best particle (key) of the swarm. Update the positions of the particles by using equations (3.1-a, 3.1-b):

Step 5: If the Max_iter has been reached or if the key with fitness=1.0 value is found, then goto step 6 or else goto step 2.

Step 6: Keep the best key obtained so far in the output key variables.

4.4 Experimental Results of Applying PSOCS

Two stopping criteria are used to stop the system of the PSOCS, the first criterion, is to reach the max_iter that is enough to reach this level of fitness. The second, when the fitness reaches the value equal to 1.0, then there is no need to reach the maximum number of iterations. Now we will describes the experimental results of applying PSOCS for each study case.

The best way to illustrate the proceeding of PSOCS algorithm is by looking at the development of the swarm fitness results over time.

4.4.1 Experimental Results of Applying PSOCS on SLSCC

For this study case, only 10 initial particles (keys) are appear in the swarm. The PSOCS began by generating 10 random initial particles (keys) as shown table (4.8).

Key	Strings of Swarm of SLSCC	Fitness	
1	00010111110	0.3636	
2	00110010110	0.4545	
3	01111100111	0.5455	
4	00110010110	0.4545	
5	10111111100	0.3636	
6	01110011010	0.4545	
7	11010101111	0.6364	
8	11011001100	0.5455	
9	00010111110	0.3636	
10	11011000101	0.5455	
Average of	Average of Fitness0.4727		

Table (4.8): PSOCS initialization of random initial particles for SLSCC.

As expected, none of the random keys are close to the actual key which is reflected in the fact that the average fitness for these keys is 0.4727. The best of these 10 random keys (key7) has a fitness value of only 0.6364.

After only 10 iterations, this swarm of 10 keys begins to take on a set of common features that approach the exact key: The PSOCS results after 10 generations, the initial particles (keys) as shown table (4.9).

Key	Strings of Swarm of SLCSS	Fitness
1	11010001010	0.8182
2	0000001000	0.4545
3	0000000000	0.0909
4	11010001010	0.8182
5	0000001000	0.4545
6	0000001000	0.4545
7	0000001000	0.4545
8	0000000000	0.0909
9	0000001000	0.4545
10	11010001010	0.8182
Average	0.4909	

Table (4.9): The PSOCS results after 10 generations for SLCSS.

Now the average fitness is 0.4909. The best key (key1) has fitness value of 0.8182. After 30 iterations, the swarm begins to converge at a high rate of speed.

After only 20 iterations, this swarm starts to take on a set of common features that approach the exact key: The PSOCS results after 20 generations, the initial particles (keys) are shown table (4.10).

Key	Strings of Swarm of SLCSS	Fitness
1	1000000100	0.9091
2	0000000100	0.3636
3	1000000100	0.9091
4	0000000100	0.3636
5	0000000100	0.3636
6	1000000100	0.9091
7	1000000100	0.9091
8	1000000100	0.9091
9	1000000100	0.9091
10	0000000100	0.3636
Average	0.6909	

Table (4.10): The PSOCS results after 20 generations for SLCSS.

Now the average fitness is 0.6909. The best key (key1) has fitness

value of 0.9091. After 20 iterations, the swarm begins to converge at a high rate of speed.

After 45 iterations the PSOCS is stopped since it finds the actual key as shown in table (4.11).

Table (4.11): The PSOCS finds actual key after 45 generations for SLCSS.

Key	Strings of Swarm of SLCSS	Fitness
1	1000000001	1.0000
2	11010101000	0.8182
3	11010101000	0.8182
4	11010101000	0.8182
5	0000000000	0.0909
6	11010101000	0.8182
7	01000001000	0.7273
8	11010101000	0.8182
9	11010101000	0.8182
10	1000000001	1.0000
Average	0.7364	

The average fitness is now at 0.7364, key1 and key8 turn out to have the highest fitness (1.0) and on test is the exact key.

Table (4.12), provides the iteration number for which improvement is noted in the evaluation function, together with the value of the function.

Iter.	Key	Fitness	Average	Best Initial Key
0	7	0.6364	0.4727	11010101111
10	4	0.8182	0.4909	11010001010
20	1	0.9091	0.6909	1000000100
45	1	1.0000	0.7364	1000000001

Table (4.12): Results of applying PSOSC on SLSCC.

The best initial key is: 1000000001, which is the real initial key for SLSCC.





Figure (4.3) PSOCS's results to find the actual key for SLSCC.

4.4.2 Experimental Results of Applying PSOCS on LSCC

For this study case (LSCC), 10 initial particles (keys) are appear in the swarm. The PSOCS began by generating 10 random initial particles (keys) as shown table (4.13):

Table (4.13): PSOCS initialization of random initial particles for LSCC.

Key	Strings of Swarm of LSCC	Fitness
1	101100011010	0.4167
2	111001011011	0.7500
3	000010011001	0.5000
4	000101010011	0.5000
5	111001011011	0.7500
6	110100100100	0.5000
7	111011110111	0.5833
8	000010011001	0.5000
9	111011110111	0.5833
10	111001011011	0.7500
Average	0.5333	

As expected, none of the random keys are close to the actual key which is described in the fact that the average fitness for these keys is 0.5333. The best of these 10 random keys (key2) has a fitness value of only 0.7500.

Table (4.14) shows the improvement in the results of finding the actual initial key for LSCC.

Iter.	Key	Fitness	Average	Best Initial Key
0	2	0.7500	0.5333	111001011011
10	5	0.7500	0.5417	000110000000
30	3	0.8333	0.6083	011100110100
50	1	0.8333	0.6167	011010010101
120	2	0.9166	0.6333	010111010110
219	9	1.0000	0.6583	100011000001

Table (4.14): Results of applying PSOSC on SLSCC.

The best initial key is: 100011000001, which is the actual initial key. Figure (4.4) shows the achievement of PSOCS to find the actual key for SLSCC.



Figure (4.4) PSOCS's results to find the actual key for LSCC.

4.4.3 Experimental Results of Applying PSOCS on NTSCC

For another example of attack non-linear function, we have the NTSCC, only 10 initial keys were in the swarm. The system began by generating 10 random initial key as shown table (4.15):

Key	Best Key	Extended Strings of Swarm of NTSCC	Fitness
1	00100010000	000000000100000000000100000000000000000	0.5106
2	00010010000 1	000010001000000000100001000010000000000	0.5319
3	00001001000 1	0101010101011101111011100000110110000011011	0.4894
4	01000010000 1	0000101100000000010110000001011000000101	0.4468
5	00100010000	11011101110110011100111001110011100110000	0.4043
6	00010110000 1	00000111011100000111001110000000111001110011100	0.5745
7	01100010000 1	00000001011000000000111101111000000111101111	0.4468
8	00100011000	000000001110000000001011000000101101011010	0.4468
9	00010010100	00000111011100000111001110000000111001110011100	0.5745

Table (4.15): PSOCS initialization of random initial particles for NTSCC.

10	01000100000 1	1011101110110110101101011010100000011010	0.4894
	Average of Fitness		0.4787

We notice that, none of the random keys are close to the actual key which is described in the fact that the average fitness for these keys is 0.4787. The best of these 10 random keys (key6) has a fitness value of only 0.5745.

Table 4.16 shows the improvement in the results of finding the real initial key for NTSCC.

Table (4.16): Results of applying PSOSC on NTSCC.

Iter.	Fitness	Ave.	Best Key	Extended Best Initial Key
0	0.5745	0.4787	011011111100	00000111011100000111001110000000111001110011100
20	0.6596	0.5372	101001001000	001000000100100000000100000000000000000
50	0.7021	0.5670	101011110010	0111000001111001000000100100000010010100101
100	0.7021	0.5957	101010110100	0101000001011010000000101000000010100000
200	0.7447	0.6915	101100100100	100100001001001000000001000010000000000
384	1.0000	0.7281	101100110001	100100001001100010000100011000100000000

The best initial key is: 101100110001, which is the actual initial key.

Figure (4.5) shows the achievement of PSOCS to find the actual key for NTSCC.



Figure (4.5) PSOCS's results to find the actual key for NTSCC.

The attack on the class of stream ciphers must be run a number of times with a variety of parameter values. Figures (4.3), (4.4), and (4.5) present a plot comparing the values of fitness function and their averages with the number of iterations in the attack for the SLSCC, LSCC and NTSCC.



Chapter five Conclusions and Future Work

5.1 Conclusion

From this work, several conclusions can be drawn as follows:

- 1. In this thesis, we attack three study cases in stream cipher cryptosystem, these study cases are: Single LFSR, Linear System and Threshold Nonlinear system.
- 2. The results illustrated in this thesis show that the PSO has a powerful algorithm that succeeds in cryptanalysis of stream cipher cryptosystems using a small number of fitness evaluations to reach the best fitness. It also requires only a small number of particles. The actual computation times required are also small compared to other algorithms.
- 3. As the stream cipher be complicated as the needed number of generations and the consuming time are increased to find the actual initial key.
- 4. This thesis can be considered as a warning for a stream cipher designer to avoid the weak points, which may be found in the stream cipher, which are exploit by the cryptanalysts.

5.2 Suggestions for Future Work

As future work, several suggestions can be put forward to improve PSO.

1. PSOCS can be used to attack more complicated cryptosystems in the field of stream cipher (Geffe, or Bruer with more than 3 registers).
- 2. Further research in the cryptanalysis area, PSOCS can treated to be suitable to attack other complicated cryptosystems such as knapsack cipher and block cipher.
- 3. To improve the performance of PSO, we suggest making a hybrid between this algorithm and other soft computing algorithms (e.g. simulated annealing or decent algorithm).
- 4. Some improved can be done in the main evolving equations of velocity or position of particles of PSO to improve the attack achievement.



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مستخلص

ذكاء السرب طريق مبتكر لحل المشكلات الصعبة الحقيقية وهي مستوحاة من السلوك والتنظيم الاجتماعي لمجتمع الحيوانات والحشرات مثل الطيور والاسماك والنمل والنحل .. الخ.

ان امثلية السرب الجزيئي (PSO) هي خوارزمية مثالية تحاكي سلوك سرب من الطيور او الاسماك. ان سلوك السرب يتمثل بعدد من الاجسام (طيور او اسماك) في فضاء متعدد الابعاد وله خاصتين: الموقع والسرعة.

اعتبر التشفير الانسيابي من اهم فئات خوارزميات التشفير. لقد استخدمت متتابعات المسجل الزاحف بشكل واسع في كل من علم التشفير ونظرية الترميز. وهناك اساس رياضي غزير عن التشفير الانسيابي المعتمد على المسجل الزاحف، وكان هو اساس العمل في التشفير للاغراض العسكرية كونه الاساس في الاتصالات الالكترونية.

هدف البحث هو تنفيذ نظام تحليل شفري باستخدام PSO سمي نظام PSO لتحليل نظم التشفير (PSOCS) بالاعتماد على الكلمة المحتملة في اسلوب المهاجمة بالنص الواضح وباستخداد ثلاث حالات در اسية هي: مسجل زاحف منفرد باعتباره الوحدة الاساسية لنظم التشفير الانسيابي، المولد الخطي بالاضافة الى مولد يعتمد دالة العتبة (Threshold) باعتباره مولد غير خطي، حيث يقوم نظام التحليل يايجاد الحل الحقيقي لنظام المعادلات الخطية (SLE) للمسجلات الزاحفة المشاركة في المنظومة ولاي عدد من المتغيرات.

ان تنفيذ PSOCS يتمثل بمرحلتين، الاولى تتضمن بناء نظام المعادلات الخطية للمسجلات الزاحفة الخاصة بالحالة الدراسية، والثانية تمثل مهاجمة المتغيرات الخاصة بالنظام SLE والتي تمثل القيم الابتدائية للمسجلات الزاحفة. هذا البحث يظهر مدى كفاءة وانجازية PSOCS في ايجاد القيم الابتدائية للمسجلات الزاحفة.

نتائج هذا البحث تم الحصول عليها من خلال برامج معدة باستخدام لغة دلفي من الجيل العاشر وبالاستفادة من وسائل البرمجة المرئية لهذه اللغة.



وزارة التعليم العالي والبحث العلمي جامعة بغداد كلية العلوم

جمهورية العراق

من قبل

فاتن عبد الرحمن حميد

اشراف أ.م.د اياد غازي ناصر الشمري

143 V

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